

The background of the slide features a soft, hazy landscape of rolling hills and mountains under a bright, low sun. The sun is positioned in the upper left quadrant, creating a prominent lens flare effect with multiple rays of light radiating outwards. The sky is a pale, clear blue, and the overall atmosphere is serene and natural.

Initial Results of the Pol. Angle Calibration using **Sparse Wire Grid** with a Small Aperture Telescope in SO

Hironobu Nakata

- on behalf of **Simons Observatory Collaboration** -
CMB-CAL @Bicocca



This research is a part of Simons Observatory experiment, and supported by JSPS KAKENHI, Core-to-Core Program and foundations of



It is based on international cooperation involving the following institutes:



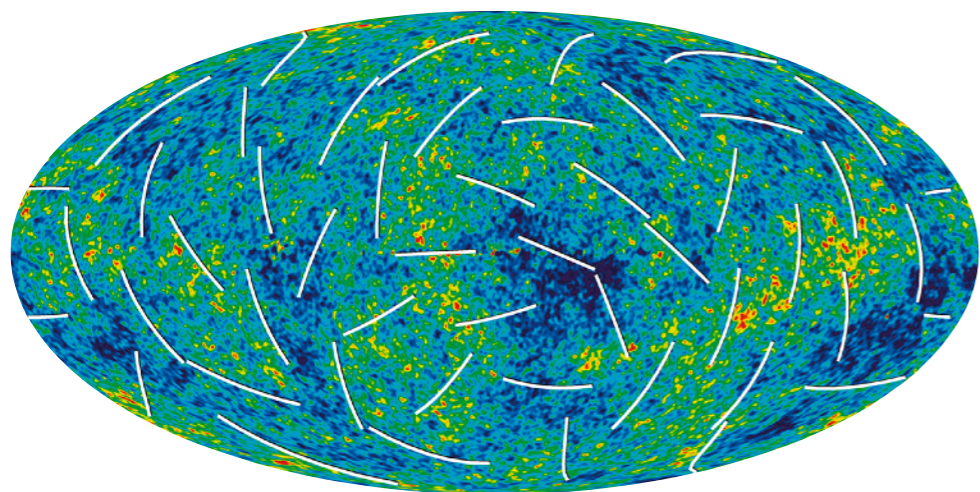
Science Goal: Primordial B-mode



Target: Primordial Gravitational Wave
≡ Evidence of the Inflation

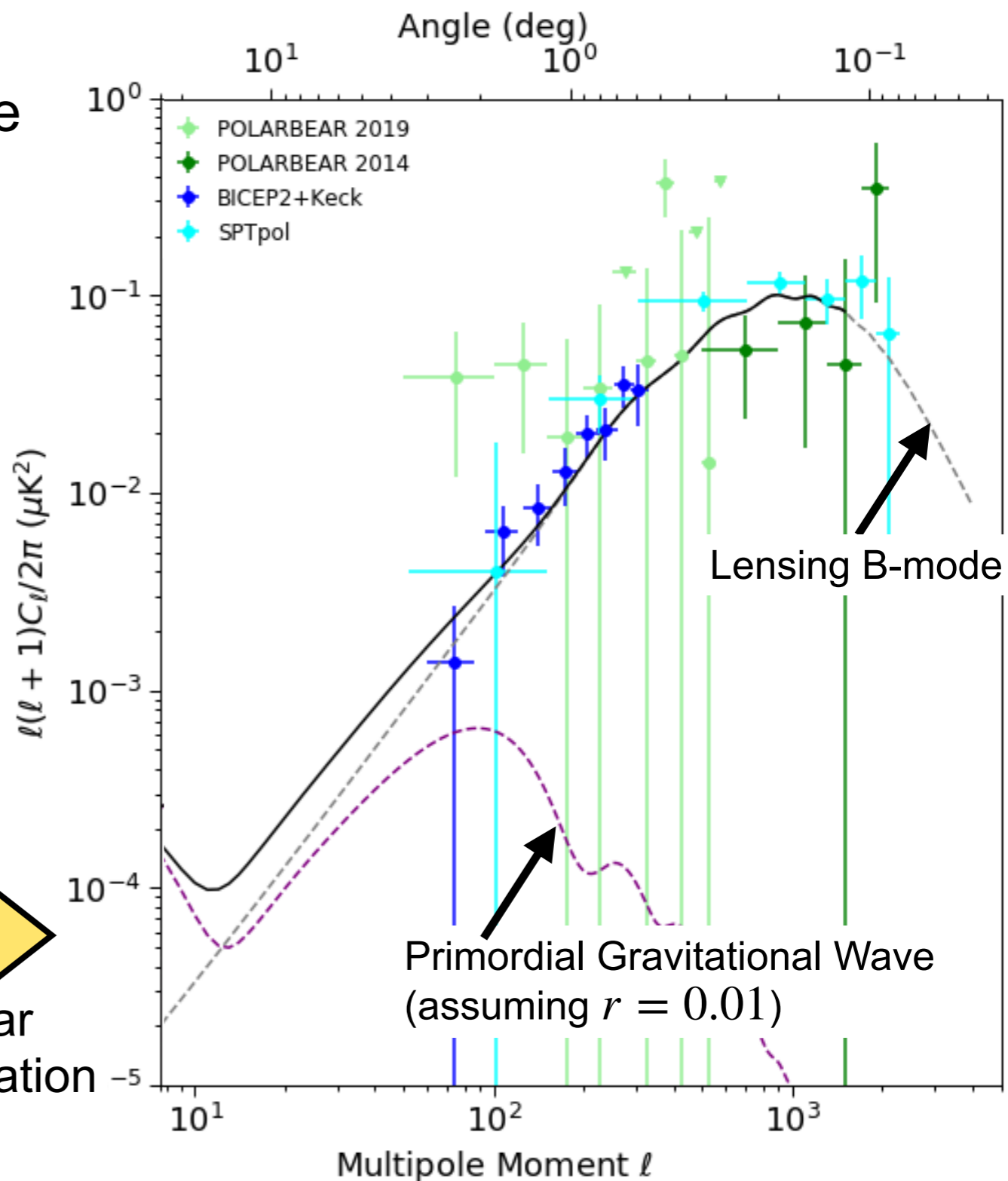
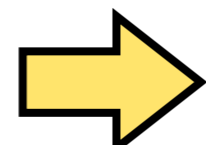
Current Limit on r :

$$r < 0.036 \text{ (BICEP2/Keck)}$$



©NASA/WMAP science team

angular correlation

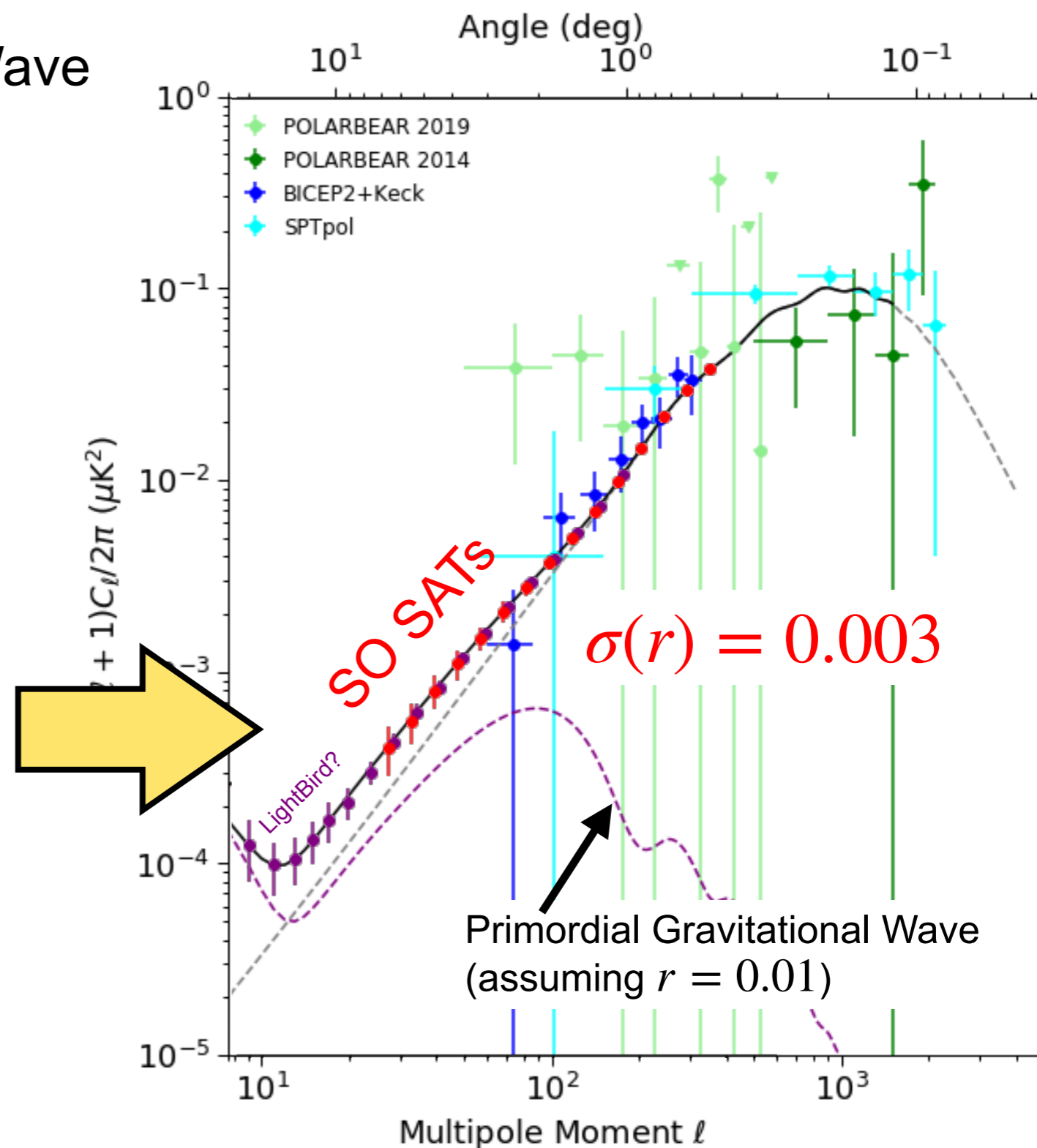
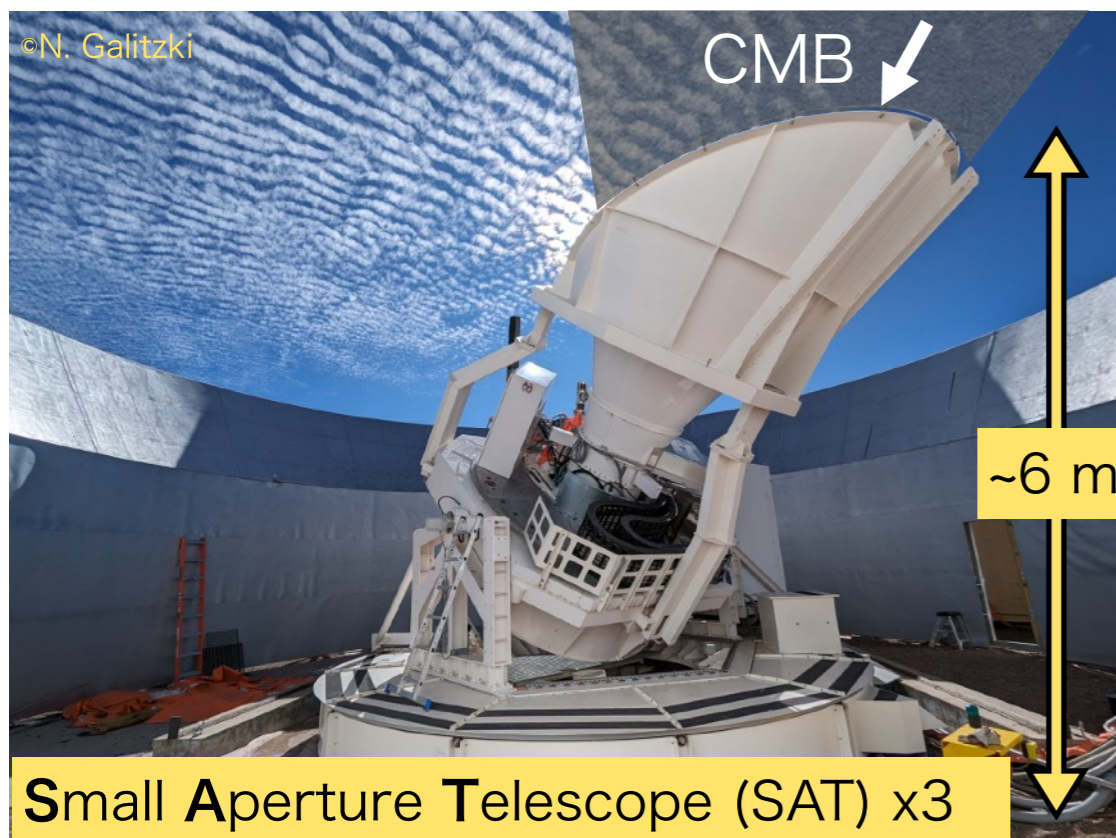


Primordial B-mode for Simons Obs.



Target: Primordial Gravitational Wave
 ≡ Evidence of the Inflation

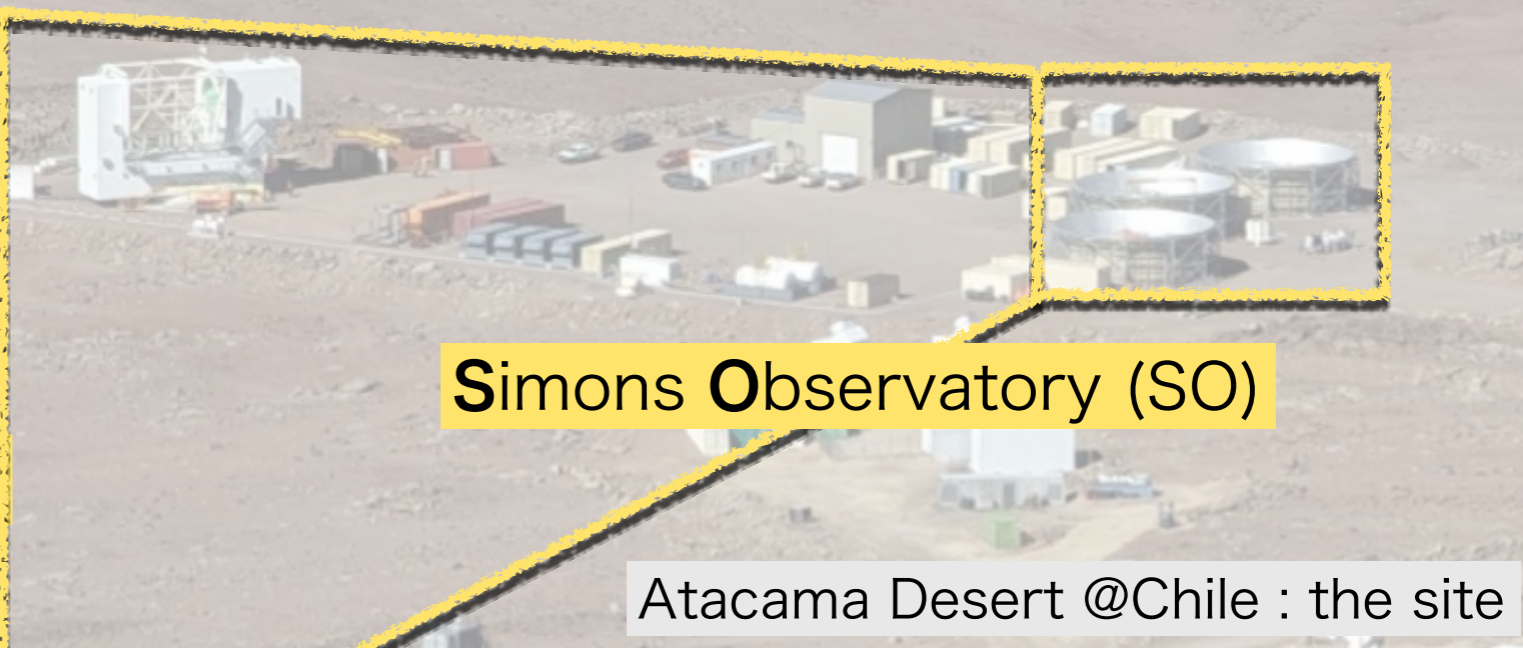
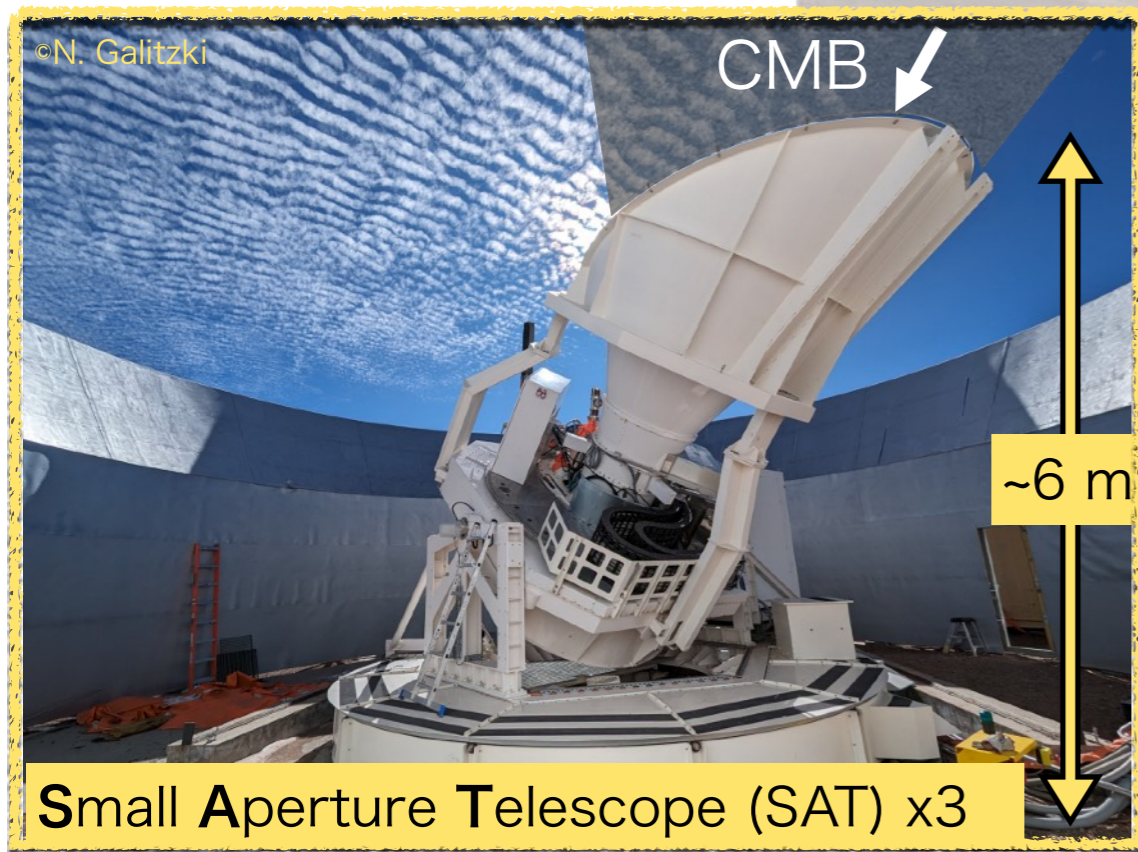
We aim to achieve
 the measurement of
 the primordial B-mode w/
 $\sigma(r) = 0.003$ [5-years observation]



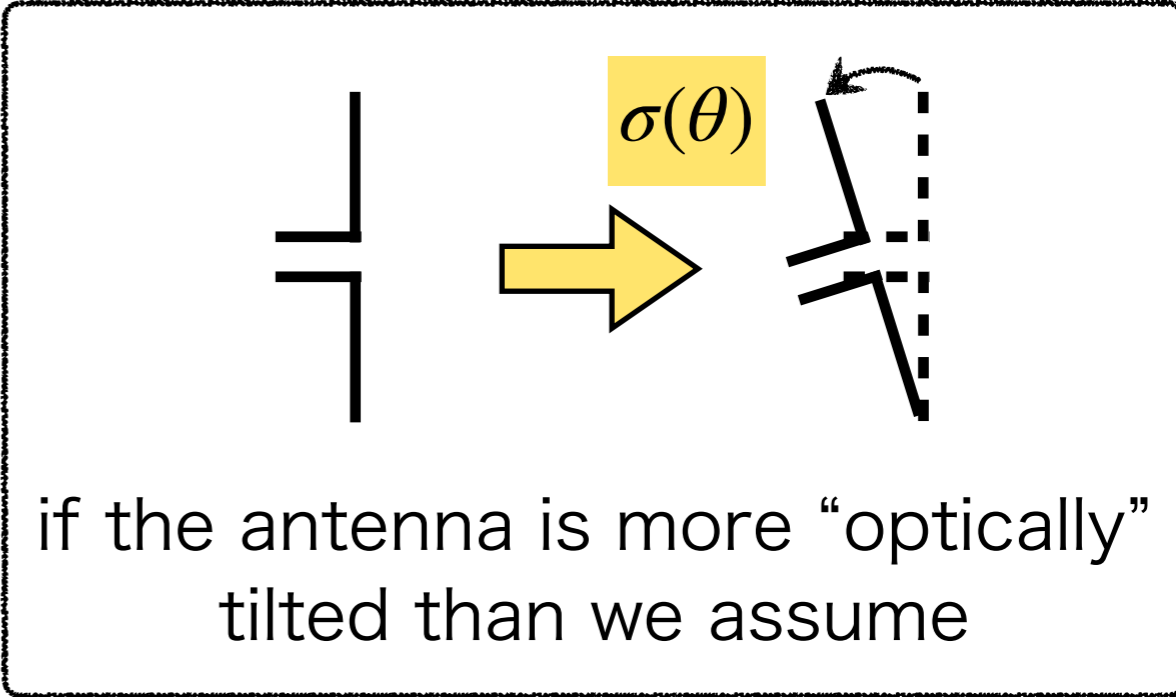
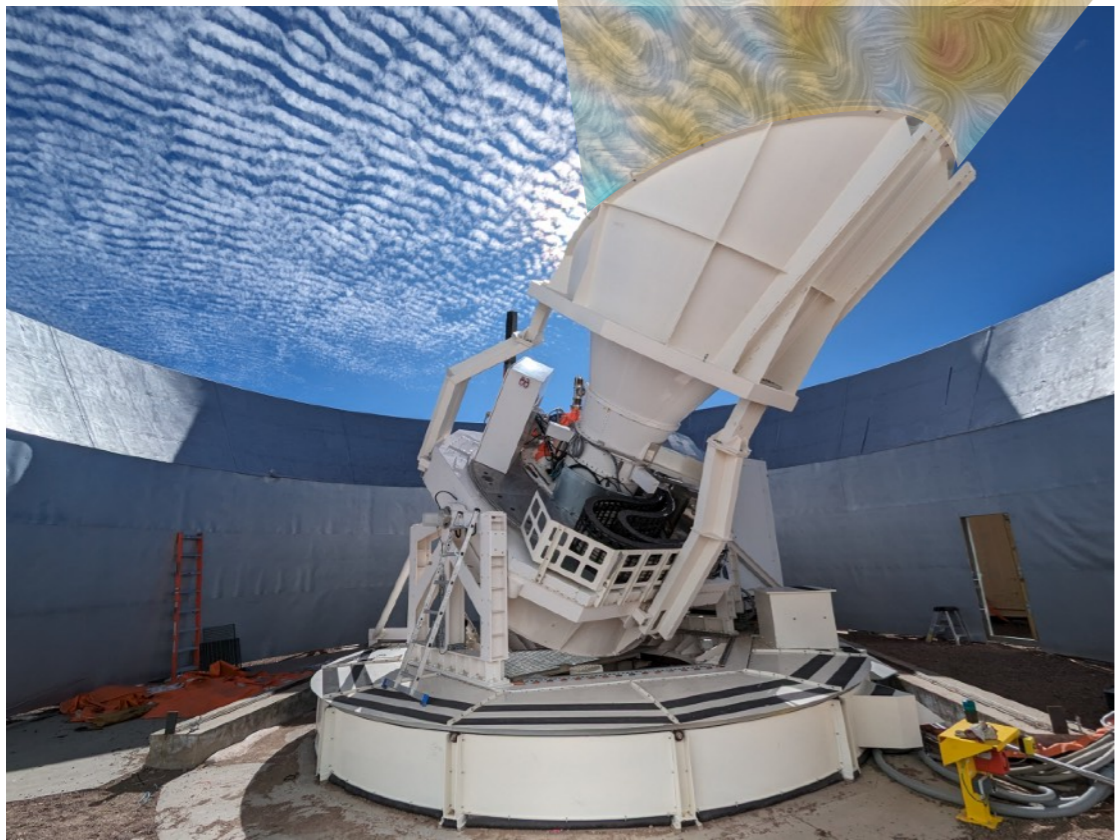
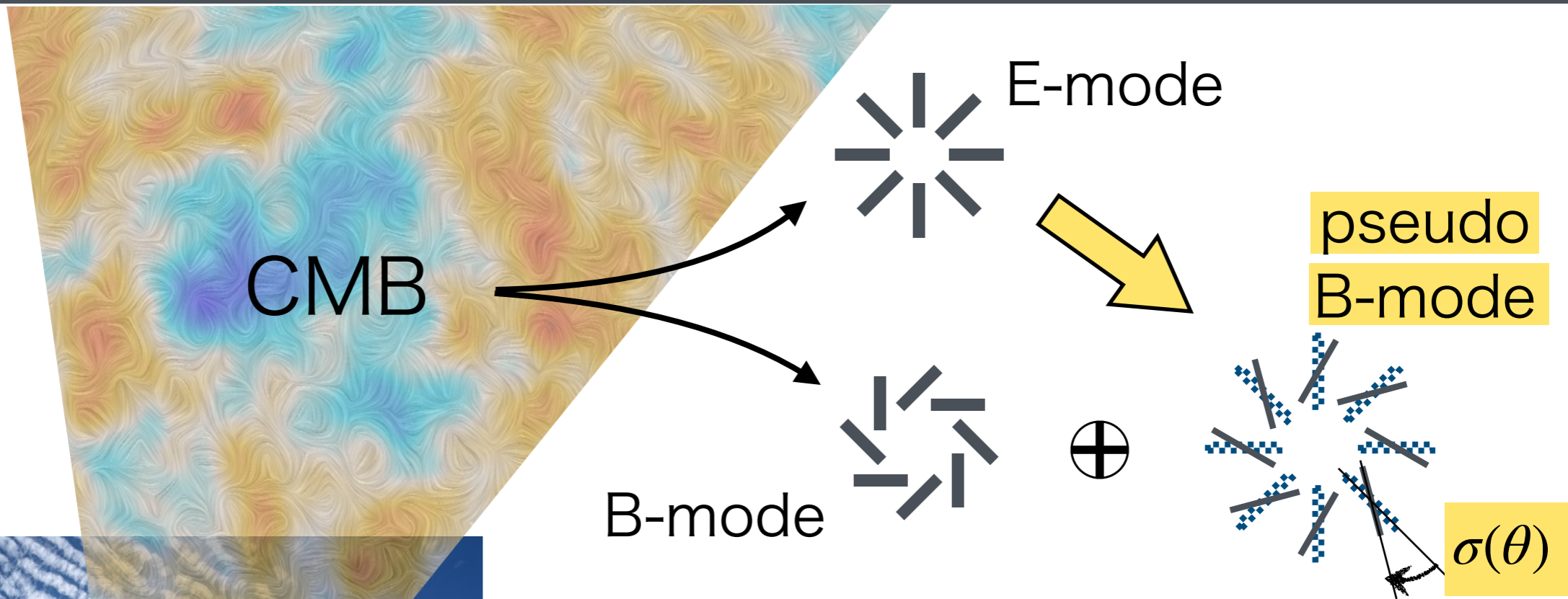
SAT in Simons Observatory



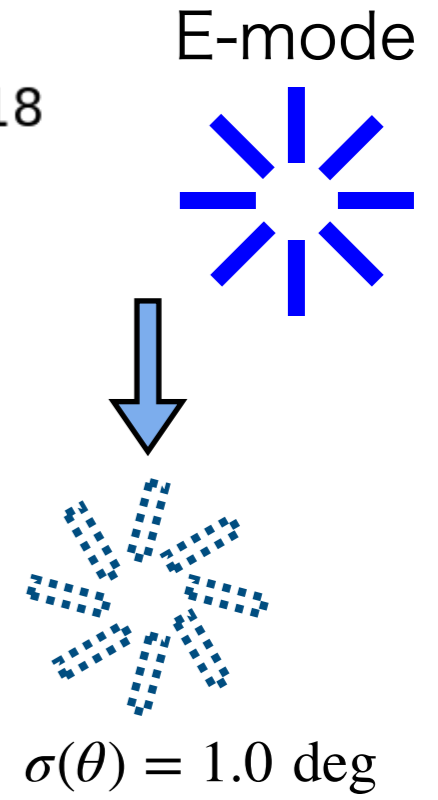
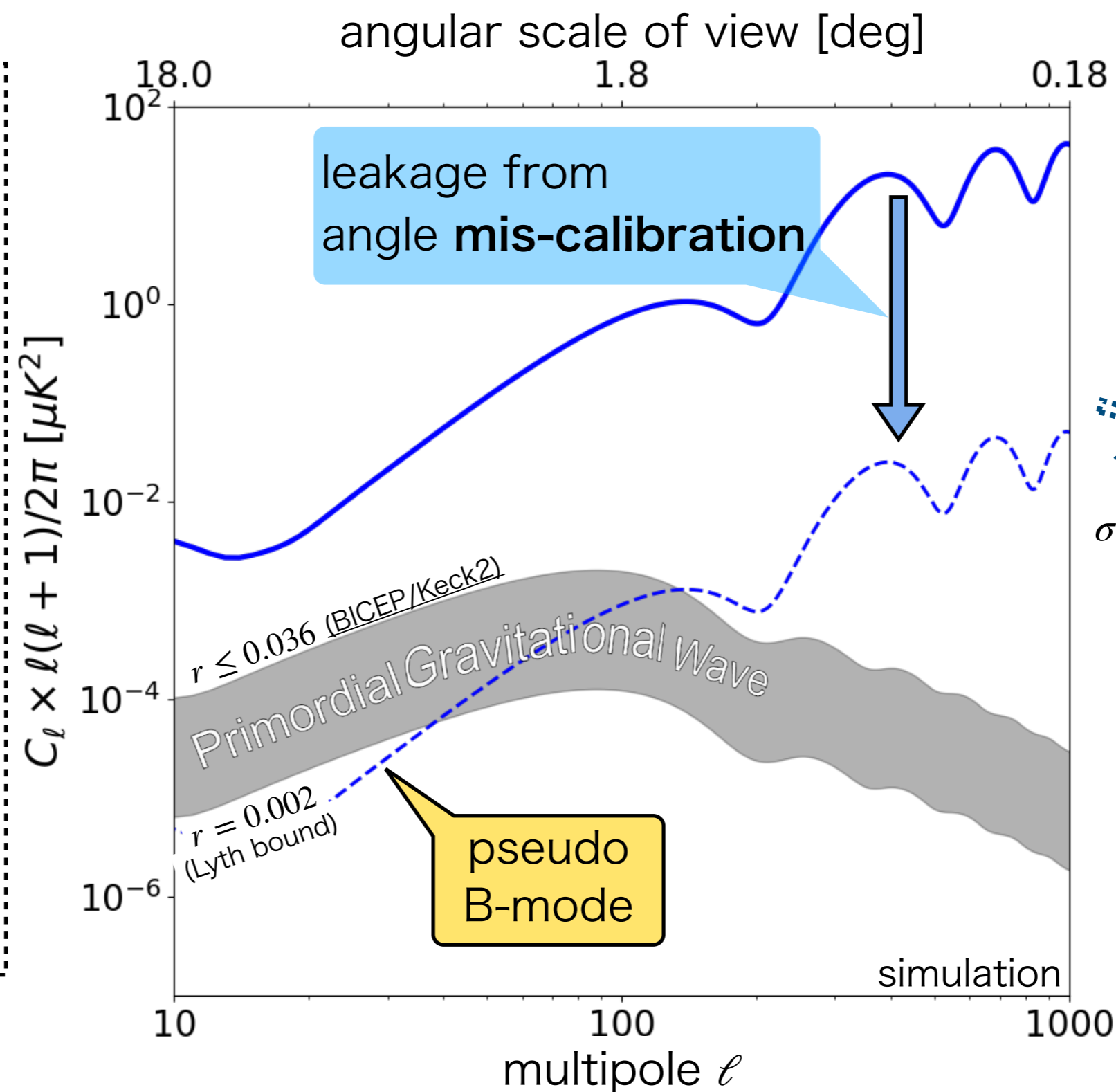
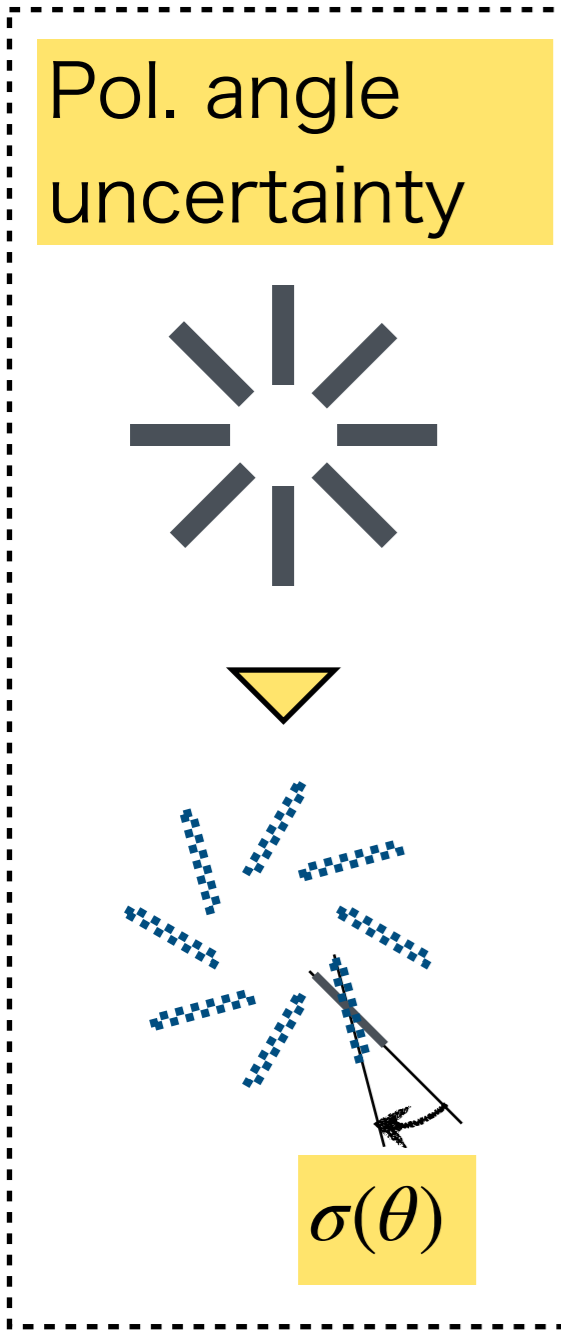
- Simons Observatory(SO) is located in Atacama Desert (Chile), 5,200 m above sea level
- SO has two kinds of telescopes for different science goals.
 - ★ **Small Aperture Telescopes (SAT) x3: large scale**
 - ★ Large Aperture Telescope (LAT) x1: small scale



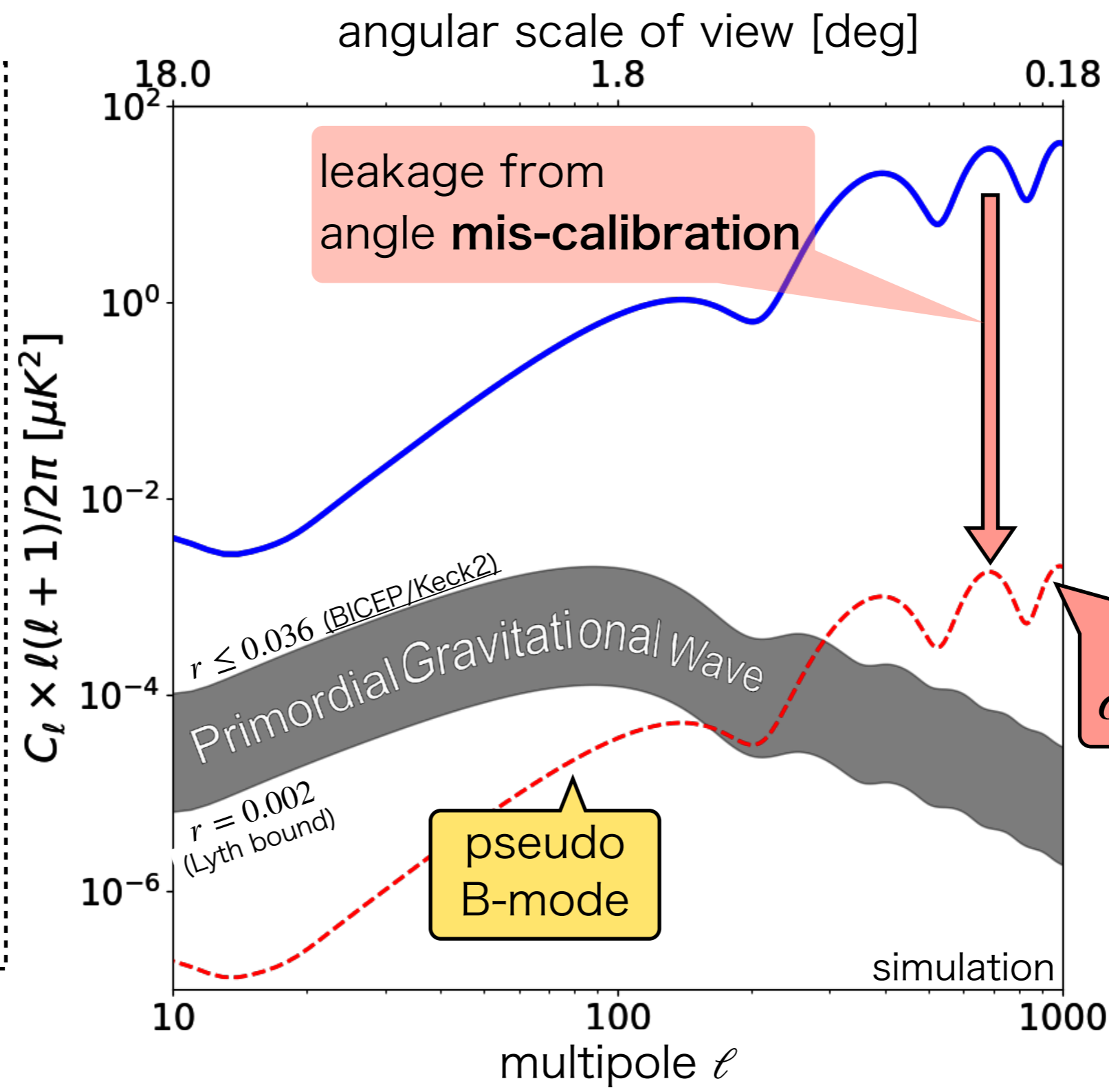
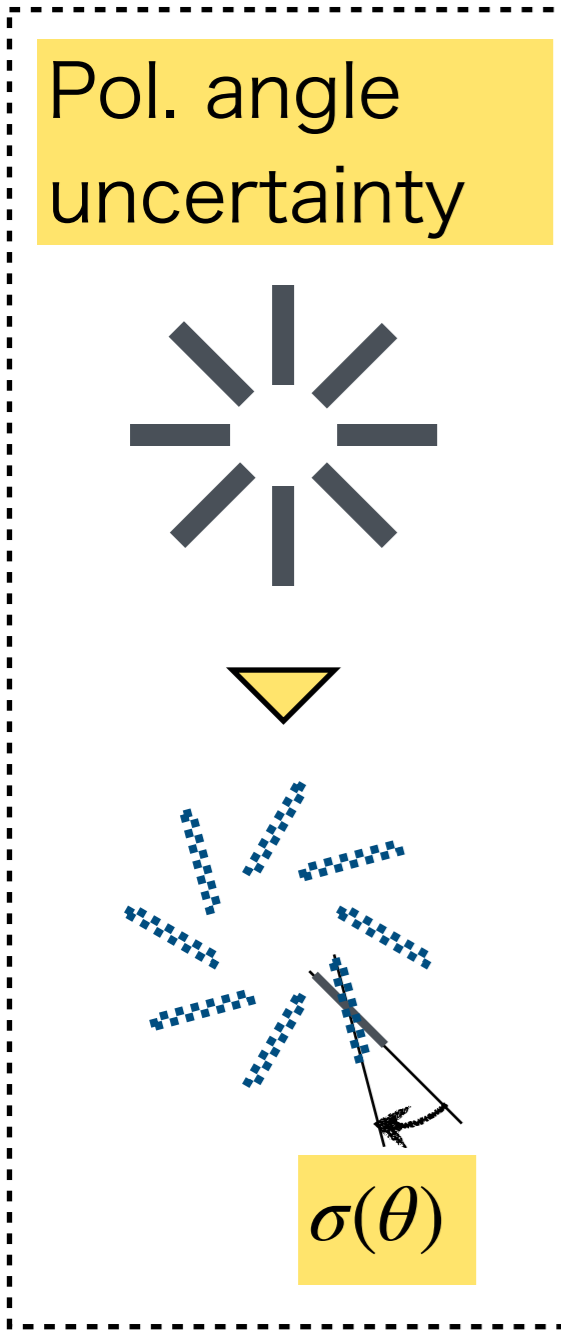
Why the Pol. Angle Calibration?



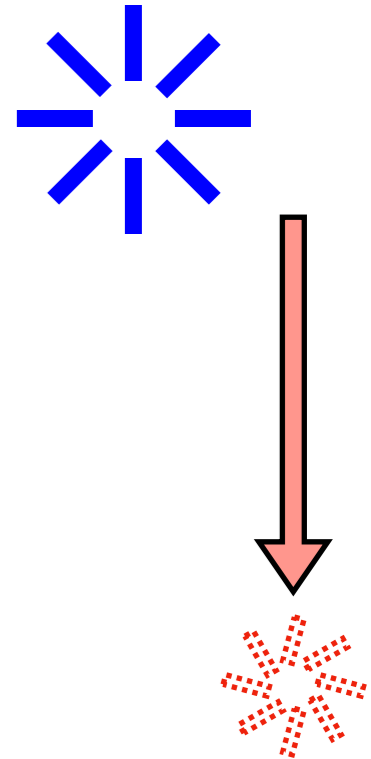
Uncertainty with 1 deg



Uncertainty with 0.2 deg

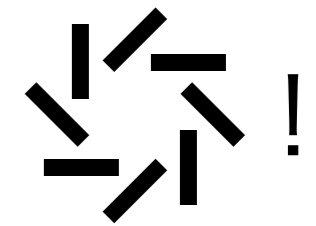


E-mode



Goal:
 $\sigma(\theta) \leq 0.2$ deg

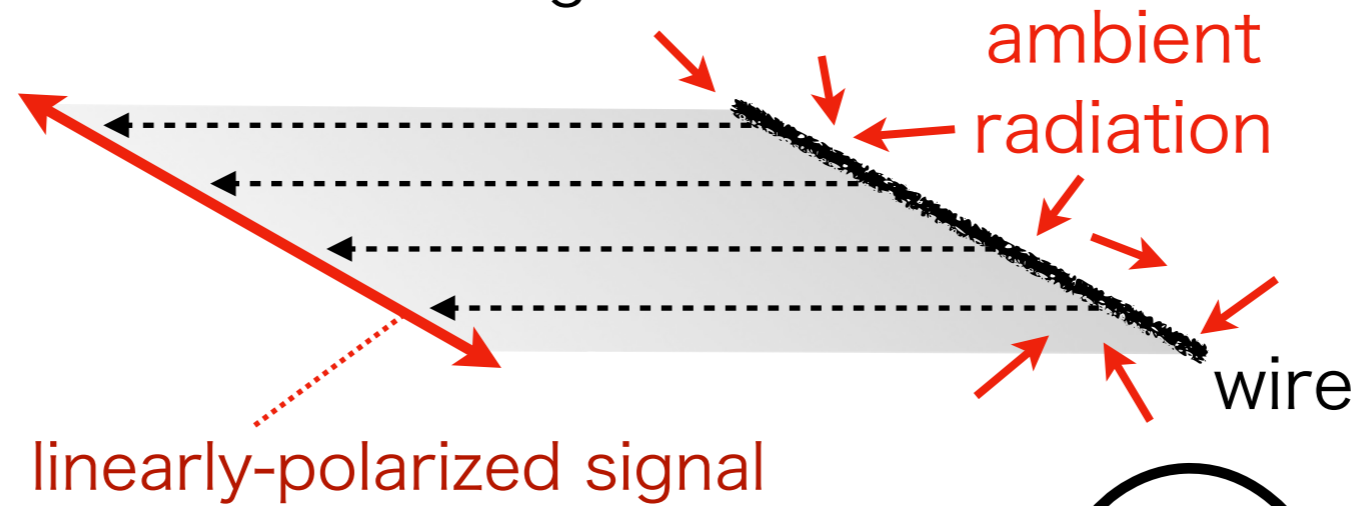
$\sigma(r) = 0.003$



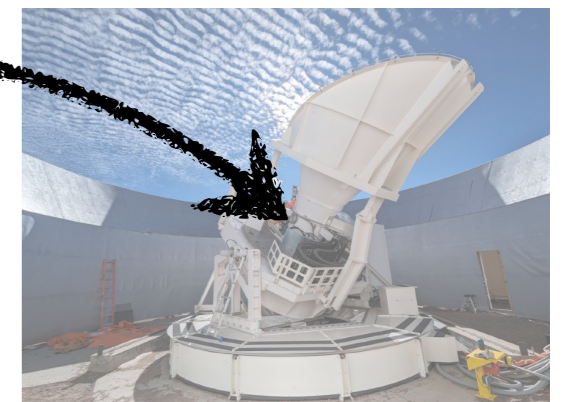
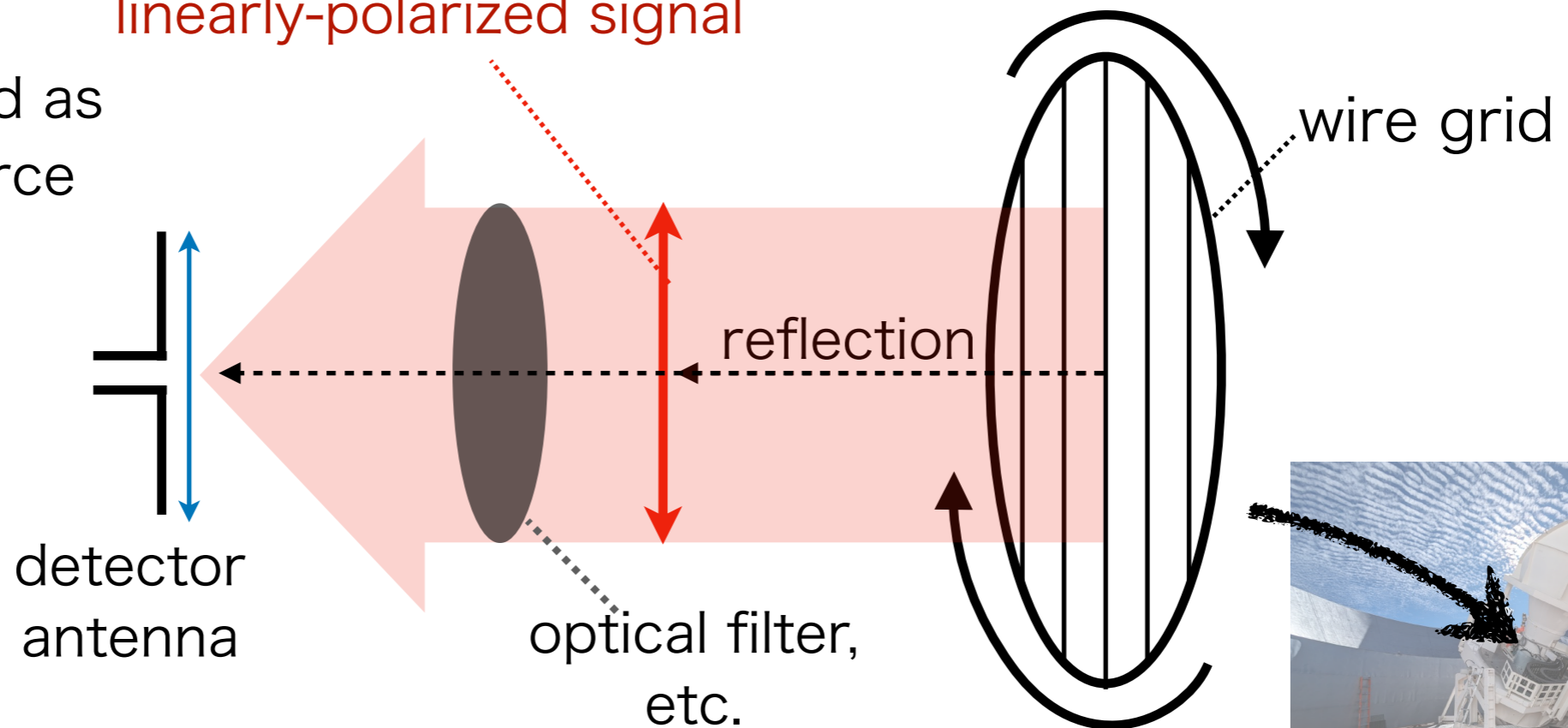
Primordial B-mode

Concepts of the calibration using wires

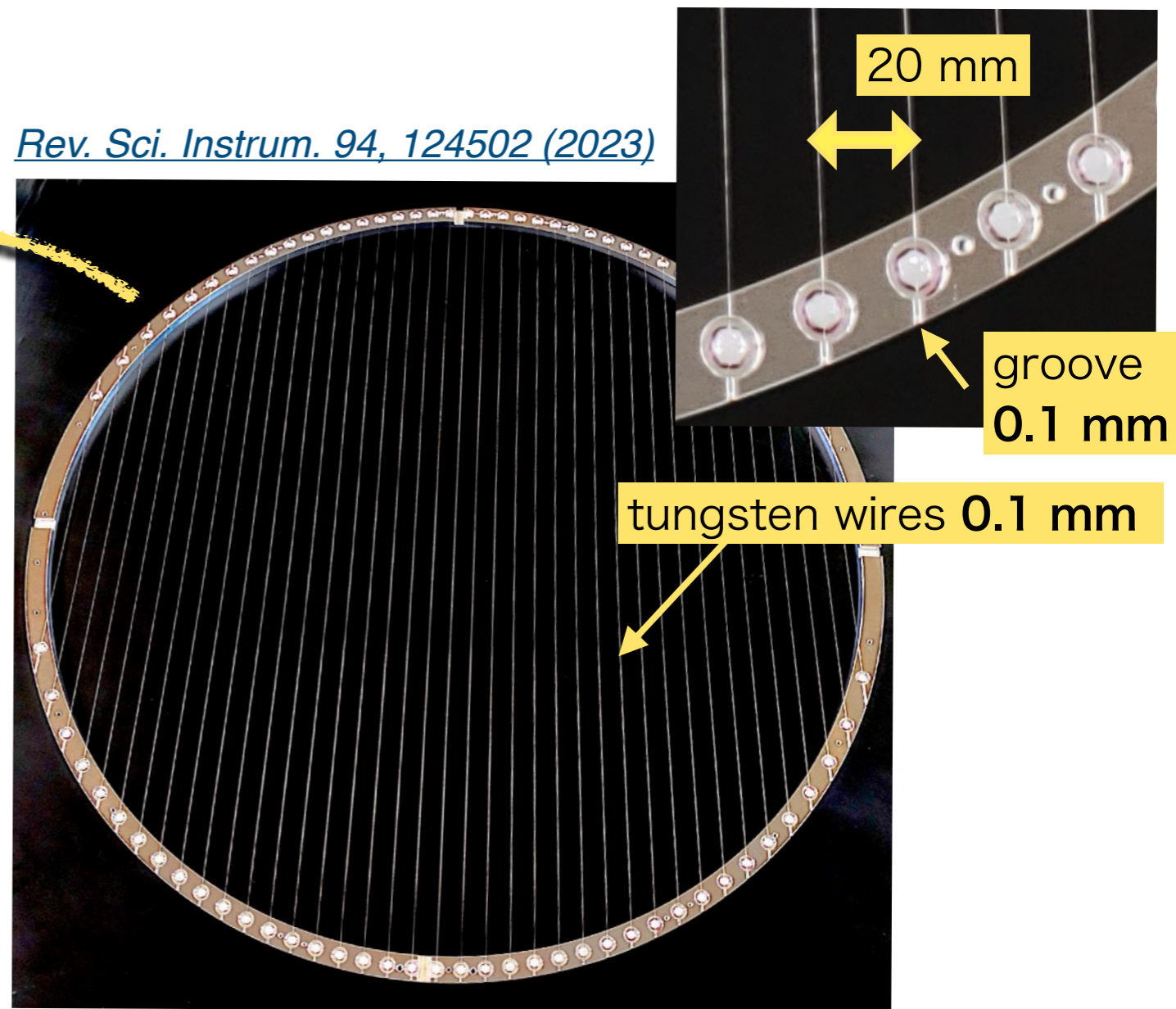
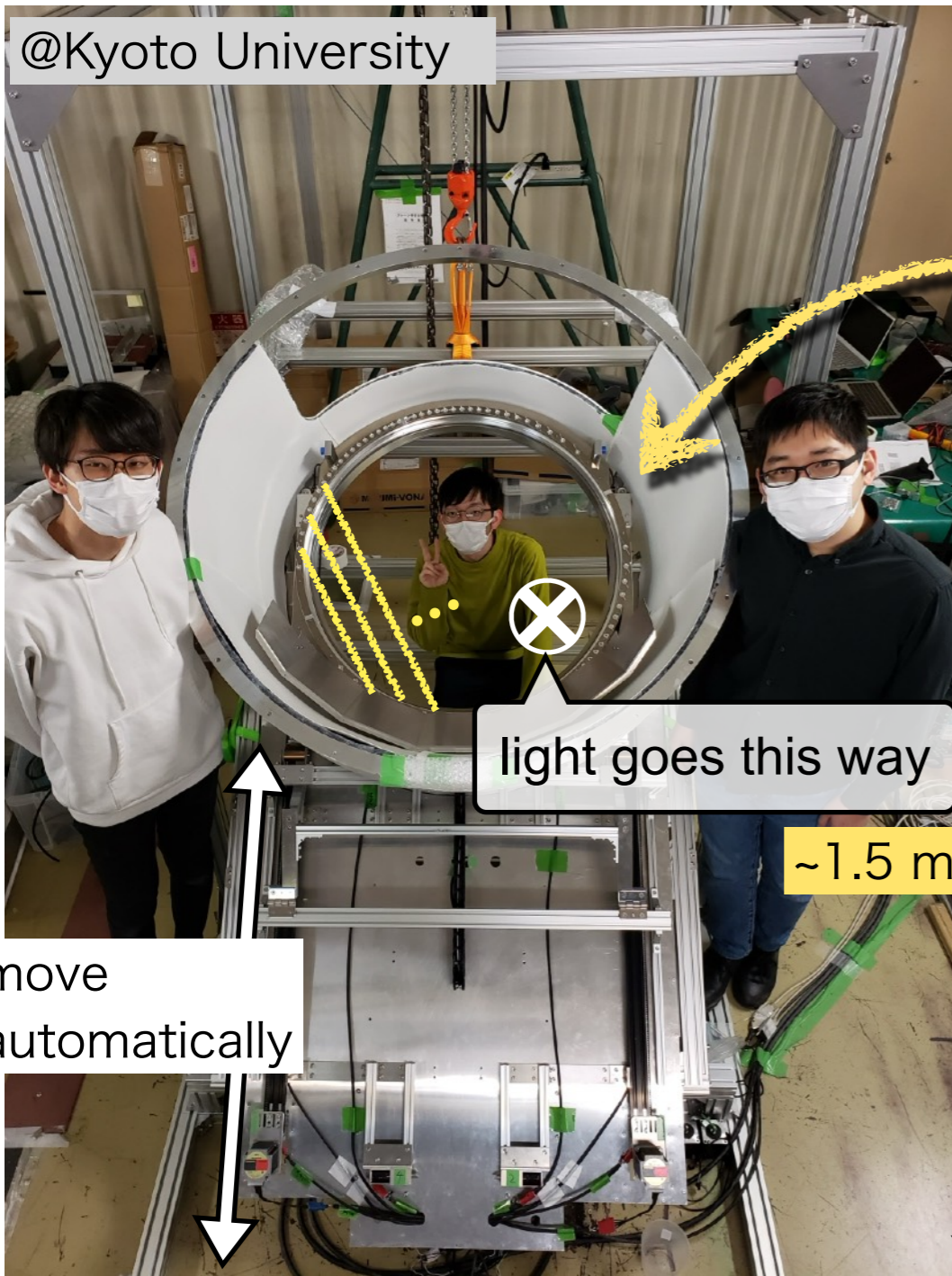
- wire creates linearly-polarized signal by reflecting radiation of its surroundings



- this can be used as an artificial source



Sparse Wire Grid Calibrator (SWG)



Sparse Wire Grid Calibrator is **equipped with automatic loading system**

The direction of wires is guaranteed by its mechanical design, and the angle is monitored very accurately ≈ 0.007 deg by an encoder →



The function of two actuators

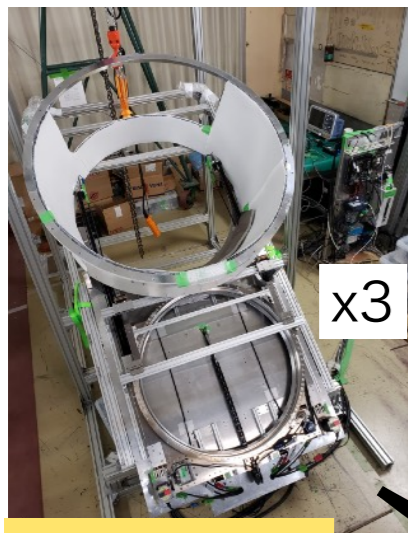


move
automatically

We can perform the calibration regularly!

Sparse Wire Grid Calibrator is **equipped with automatic loading system**

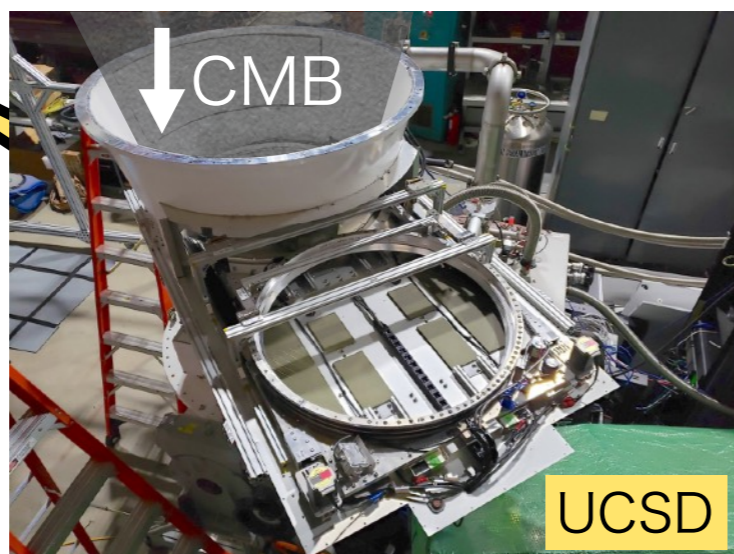
Deployment of SWG



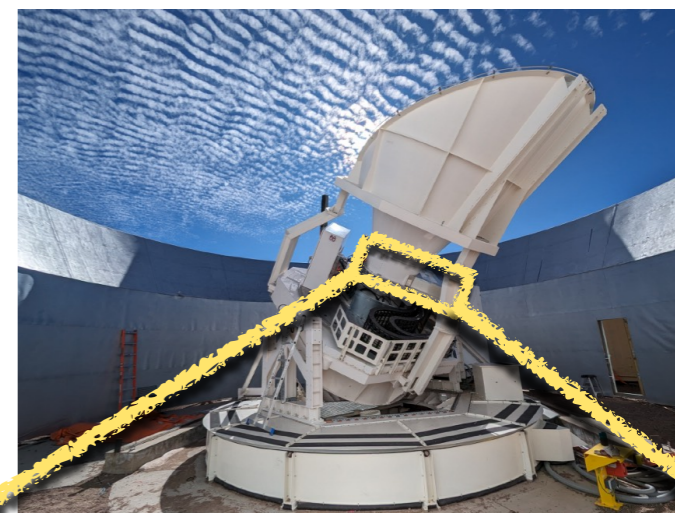
x3

Kyoto Univ.

- Development of **three calibrators** at Kyoto Univ. & UTokyo



UCSD

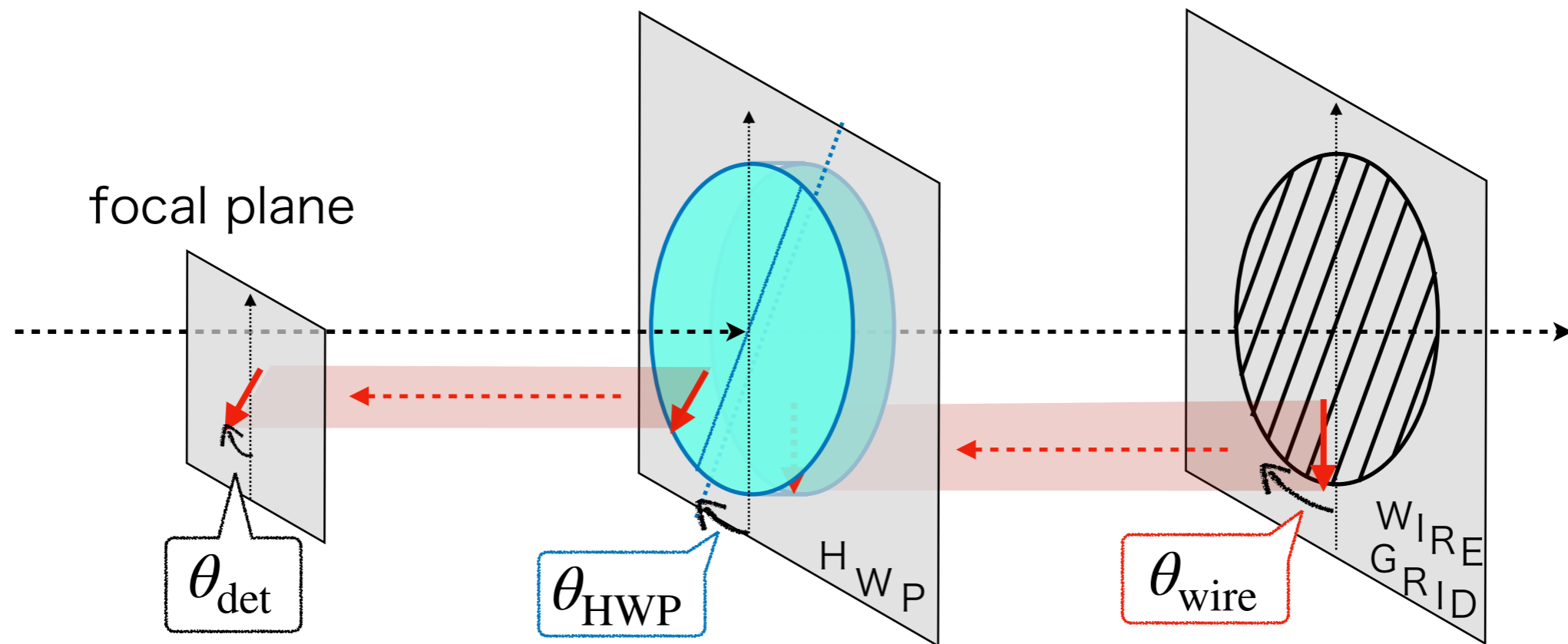


Chile

Deployed two of them:

	SAT-MF1	SAT-MF2	SAT-UHF
SWG	✓	✓	installing

Calibration method in a nut shell



0 by demodulation

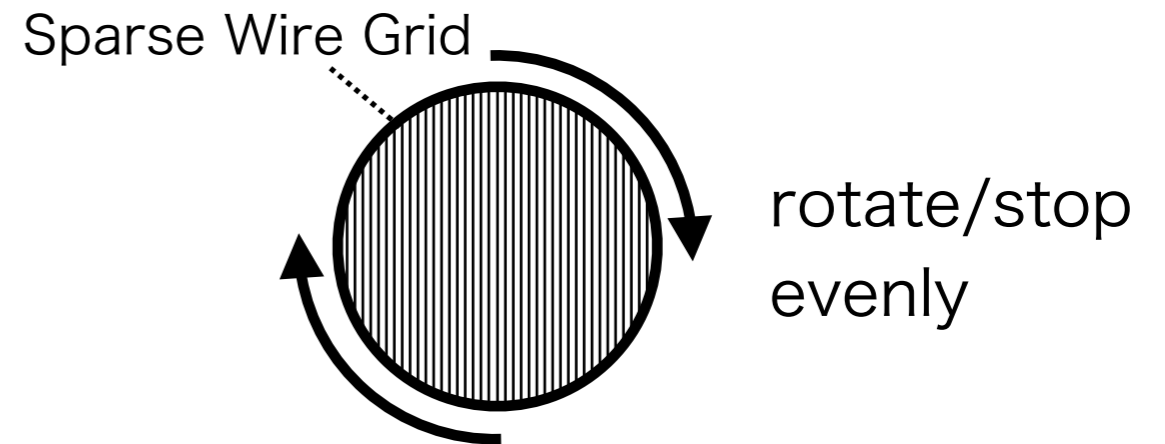
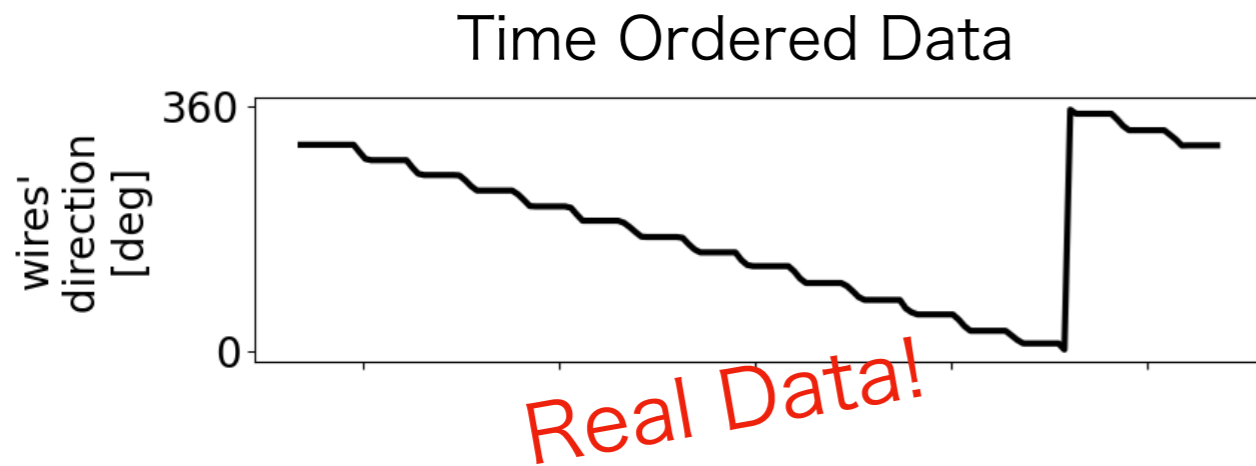
$$d_{\text{raw}} = I + \left[A_{\text{wire}} + \mathcal{O}(\varepsilon) \right] \exp i \left[-4\theta_{\text{HWP}} + 2\theta_{\text{det}} + 2\theta_{\text{wire}} \right] + c.c.$$

$$\dashrightarrow Q_{\text{wire}} + iU_{\text{wire}}$$

$$\theta_{\text{det}} = \frac{1}{2} \arg (U_{\text{wire}} / Q_{\text{wire}}) - \theta_{\text{wire}}$$

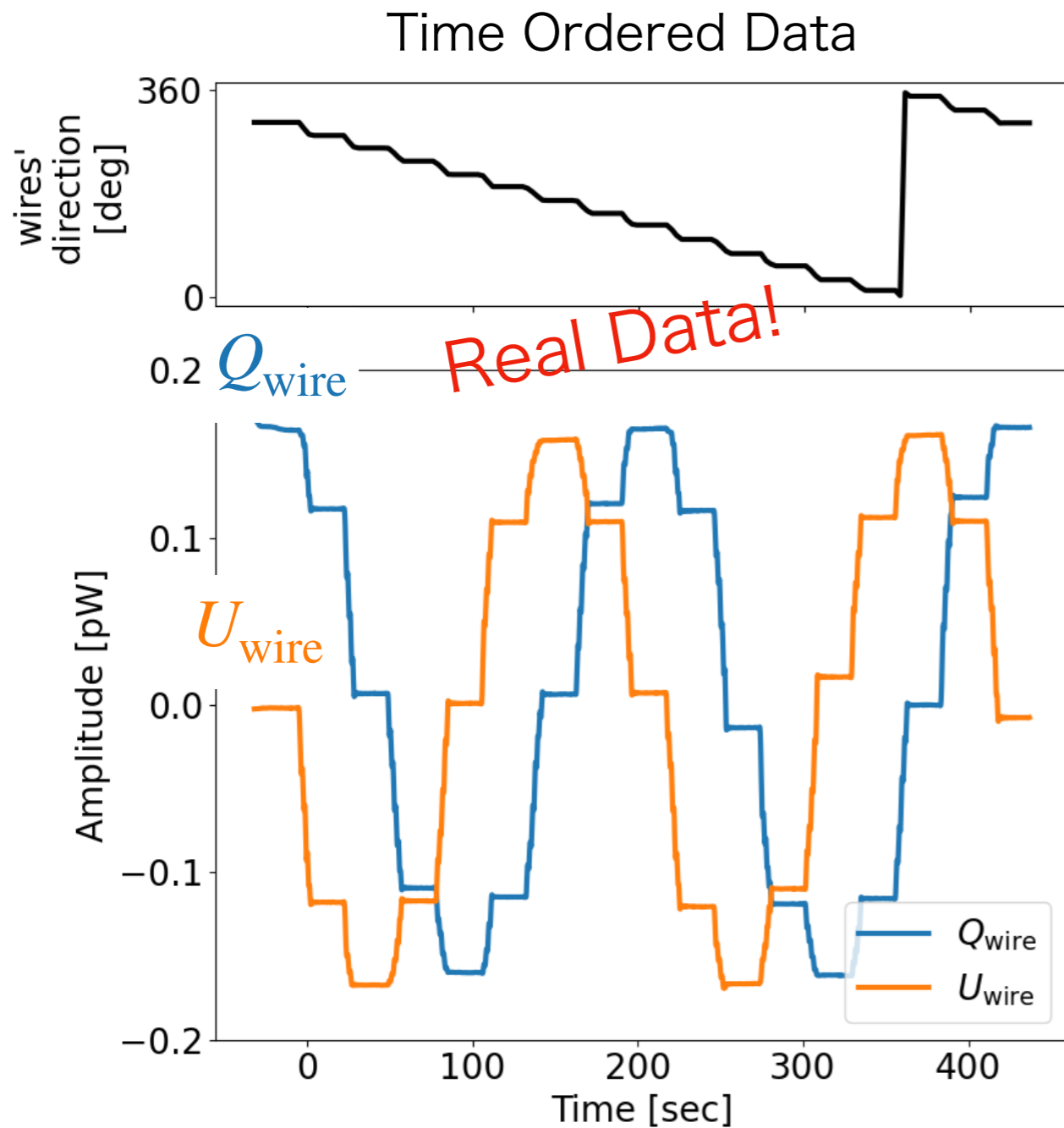
- We can use the wires' polarization as the reference for the detector response (polarization calibration)

Step 1

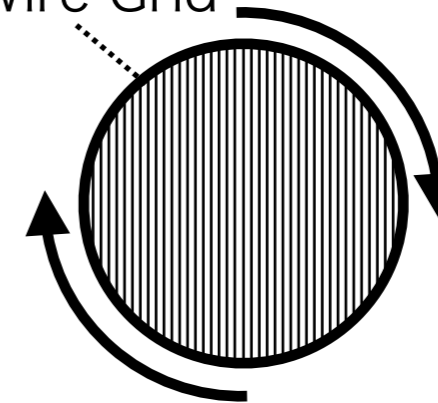


1. For example, when we stop the wire grid in 16 steps, we can see the steps in the encoder data as well.

Step 2



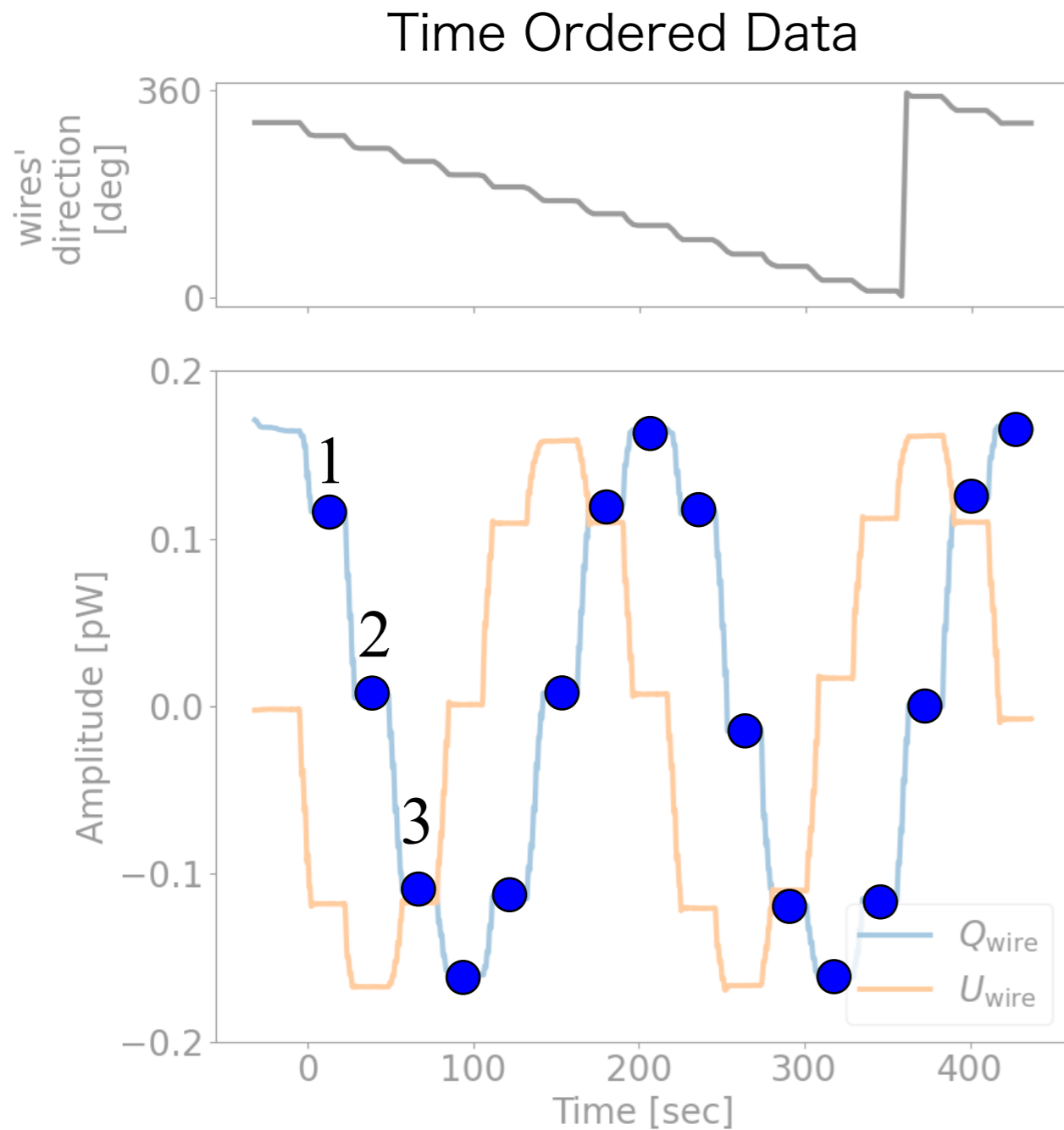
Sparse Wire Grid



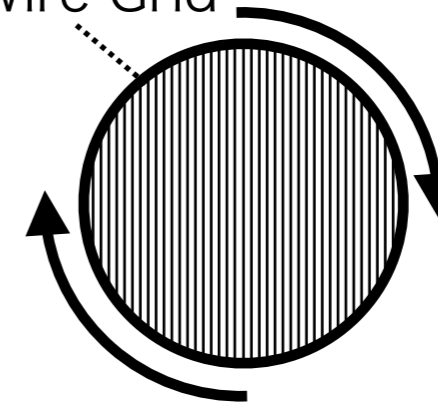
rotate/stop
evenly

1. For example, when we stop the wire grid in 16 steps, we can see the steps in the encoder data as well.
2. According to the motion of the wire grid, time streams of detectors will have step wise shapes.

Step 3



Sparse Wire Grid

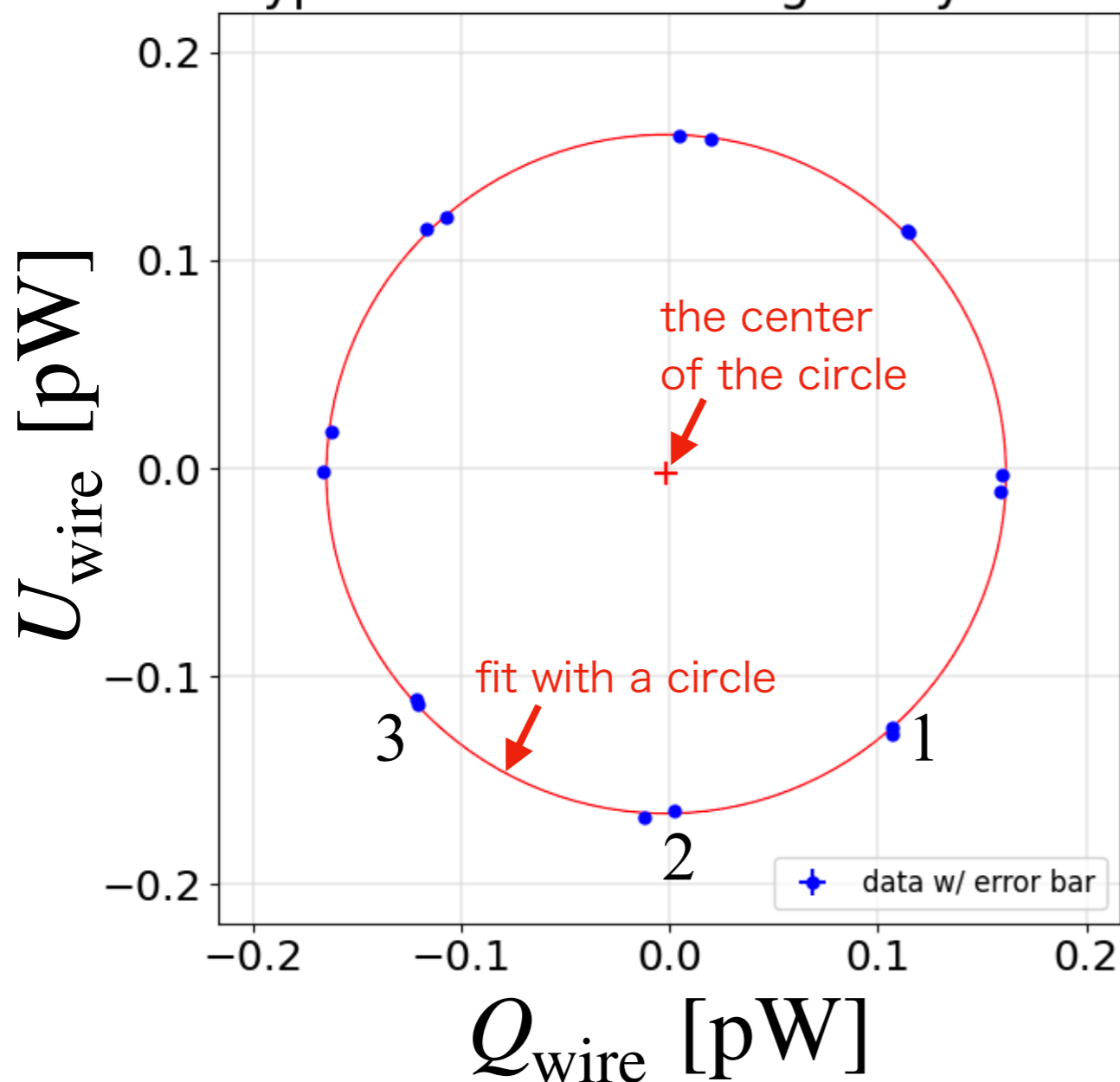


rotate/stop
evenly

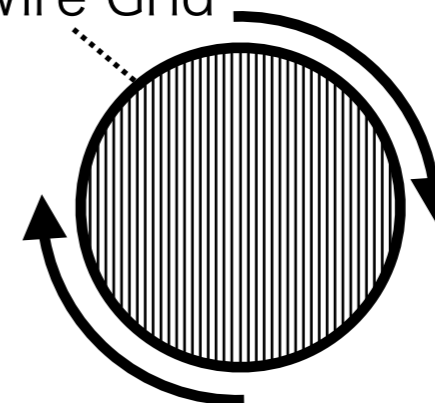
1. For example, when we stop the wire grid in 16 steps, we can see the steps in the encoder data as well.
2. According to the motion of the wire grid, time streams of detectors will have step wise shapes.
3. Further, by fitting all points together for Q and U components, we can get a circle (calibration circle).

Step 3 (cont'd)

Typical Polarization Signal by SWG



Sparse Wire Grid

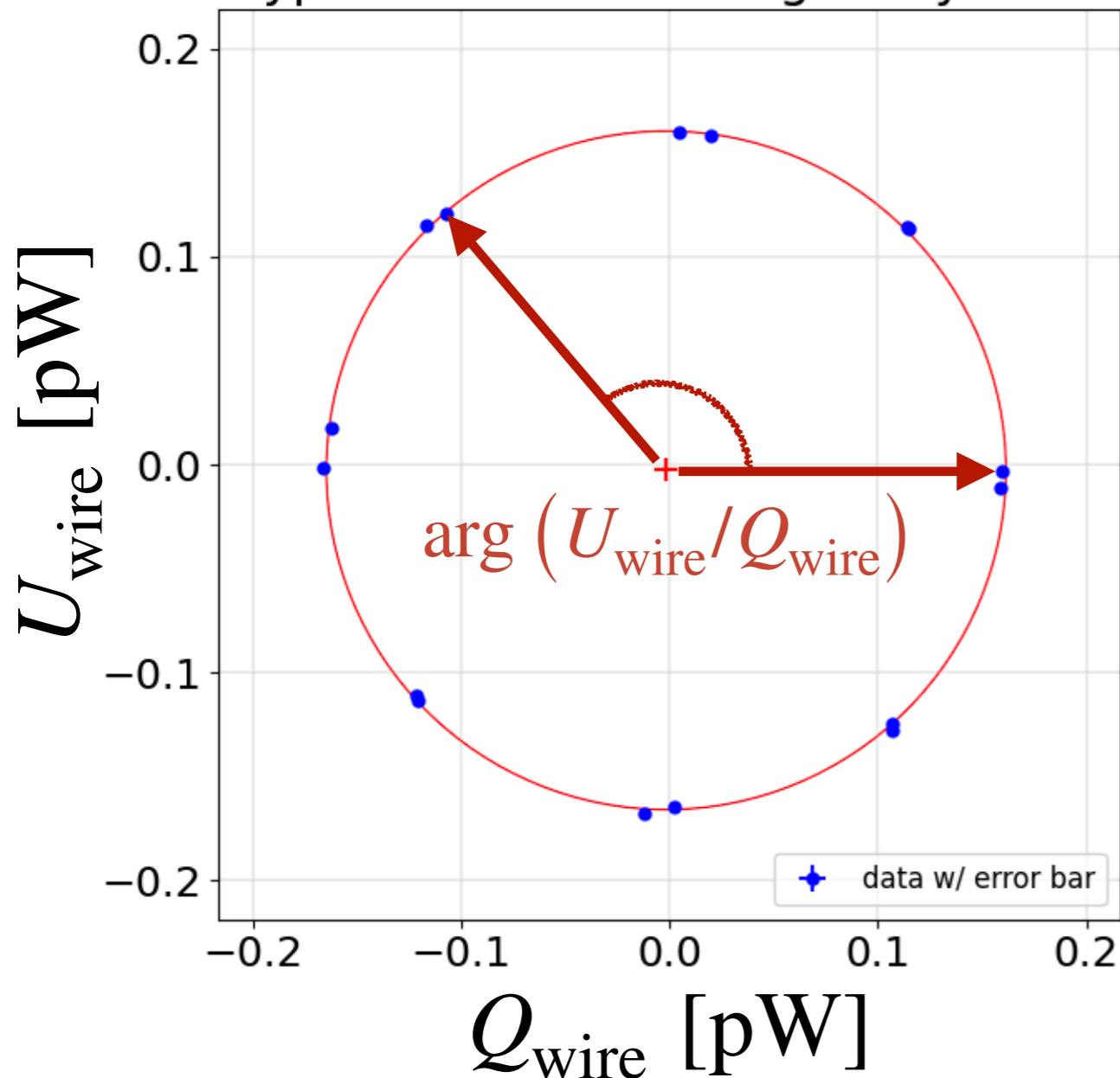


rotate/stop
evenly

1. For example, when we stop the wire grid in 16 steps, we can see the steps in the encoder data as well.
2. According to the motion of the wire grid, time streams of detectors will have step wise shapes.
3. Further, by fitting all points together for Q and U components, we can get a circle (calibration circle).

Finally

Typical Polarization Signal by SWG



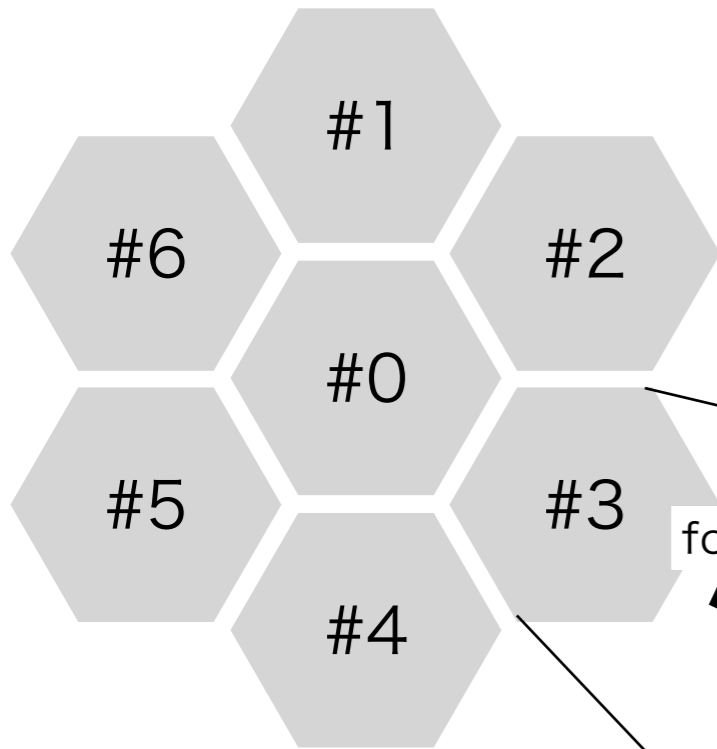
4. Finally, the calibrated angles are given by subtracting the direction of the wires.

$$\theta_{\text{det}} = \frac{1}{2} \arg(U_{\text{wire}}/Q_{\text{wire}}) - \theta_{\text{wire}}$$

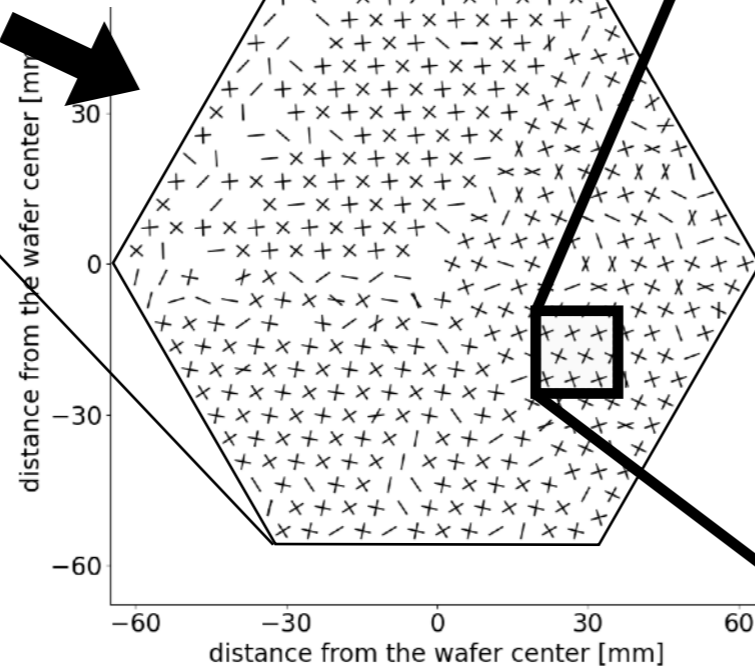
Great advantage of the calibrator is that we can **calibrate all the polarization response angle in the focal plane at the same time** (with a single calibration run).

visual check the printed design

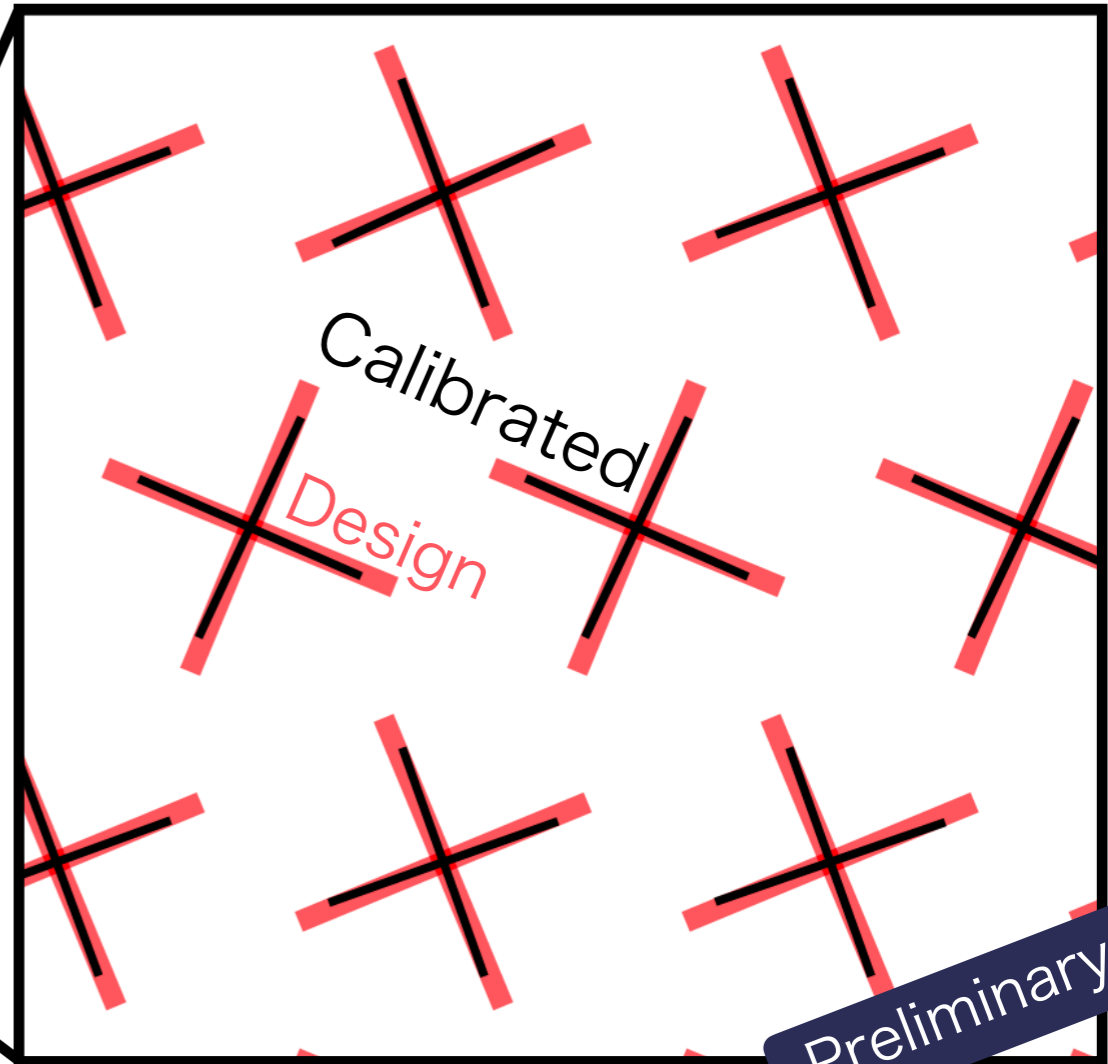
Focal Plane of SAT



for example



design angle, 150 GHz
fit angle, 150 GHz



Preliminary

Duff, S.M., Austermann, J., Beall, J.A. et al.
J Low Temp Phys **184**, 634–641 (2016).

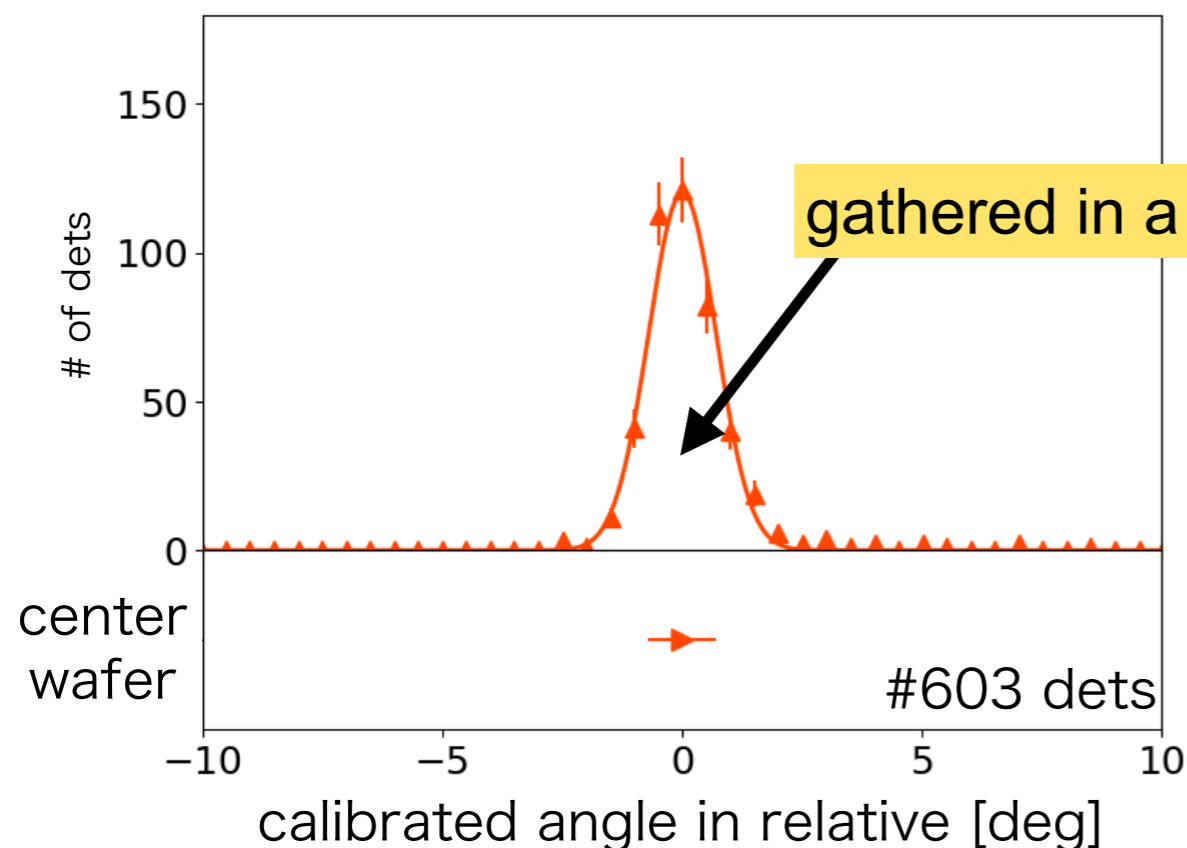
- We confirmed good agreement between the calibrated polarization angles and the design antenna pattern

Statistics of the calibration



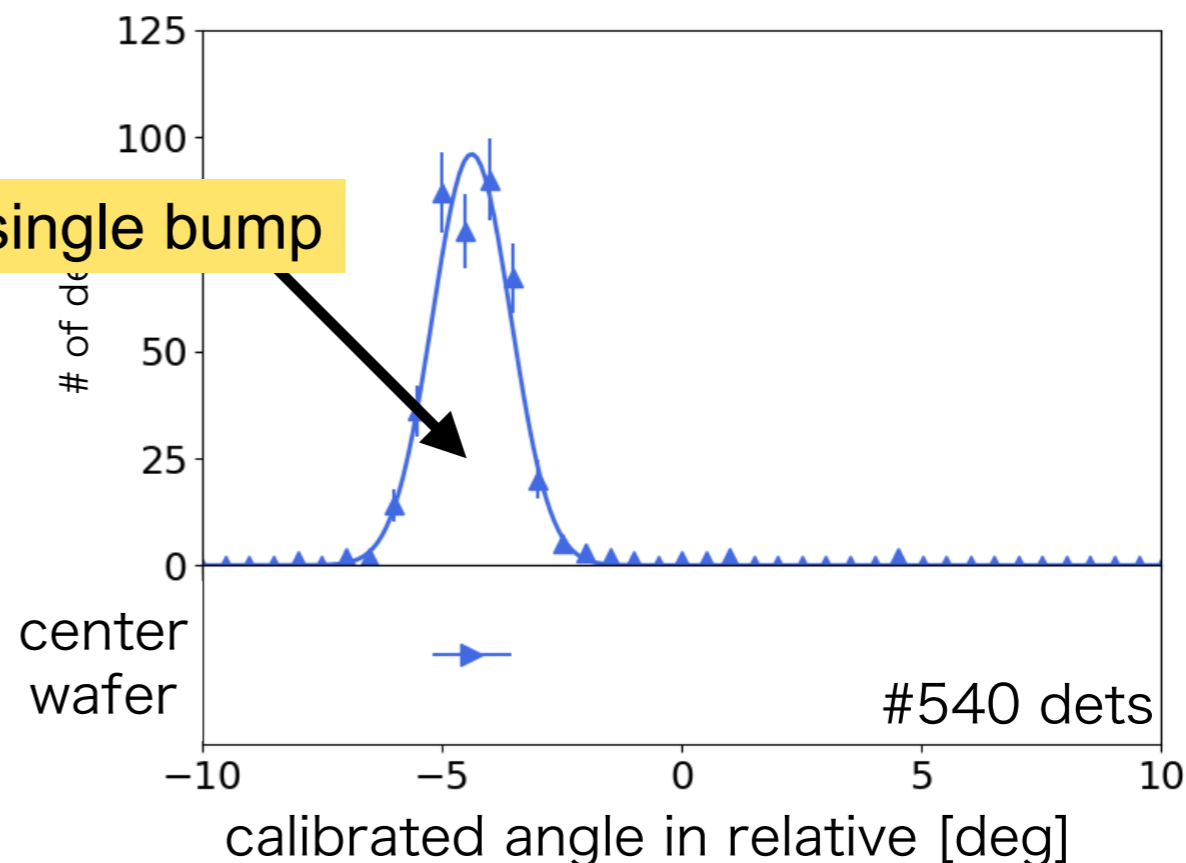
90 GHz

Calibrated Angle Stats.



150 GHz

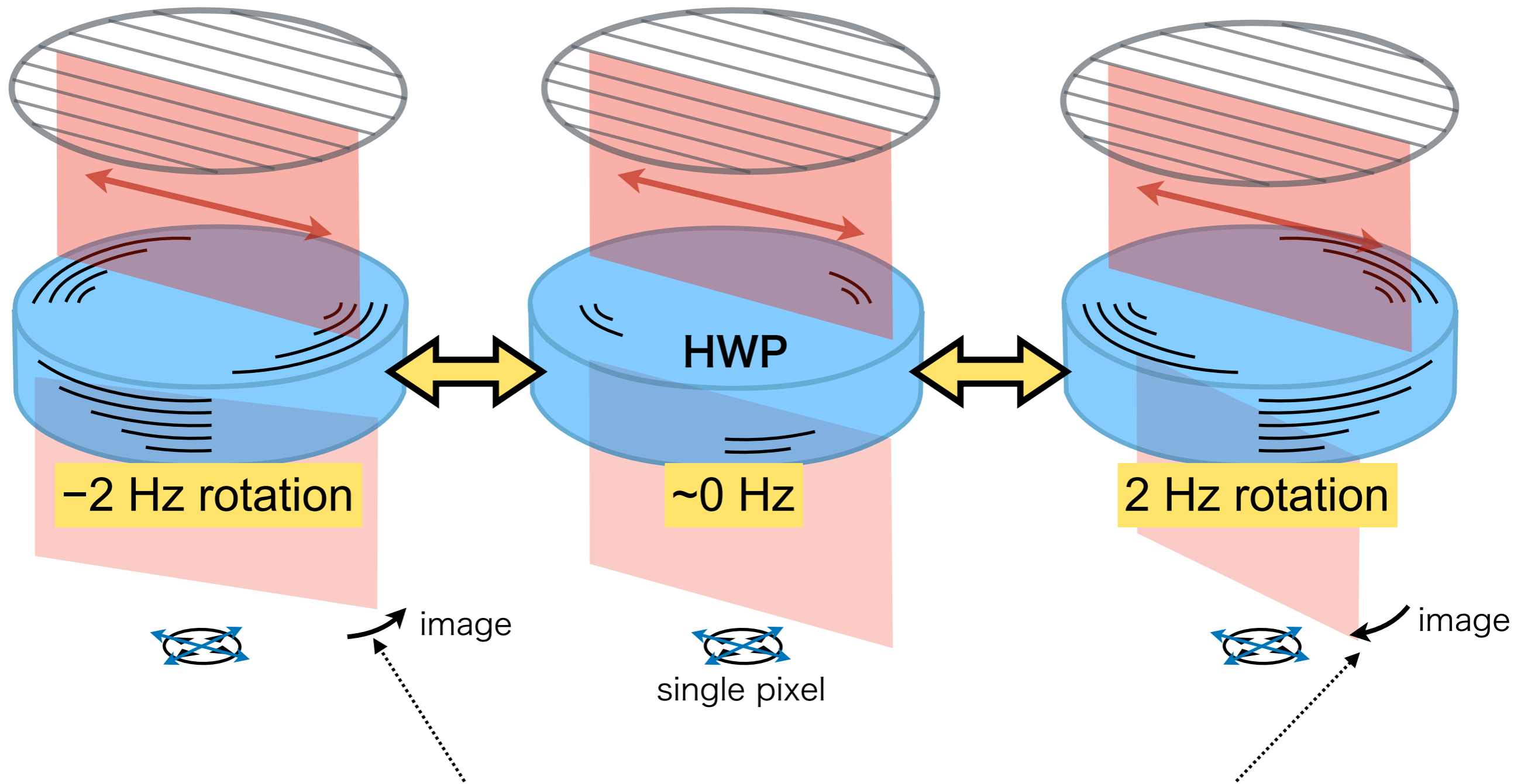
Calibrated Angle Stats.



- **Detectors' matching & calibration pipeline work very well!**
- Further, this artificial polarization source can be used **to measure the time constants of TES bolometers** → next page.

How to measure Det. time const.

Sparse Wire Grid



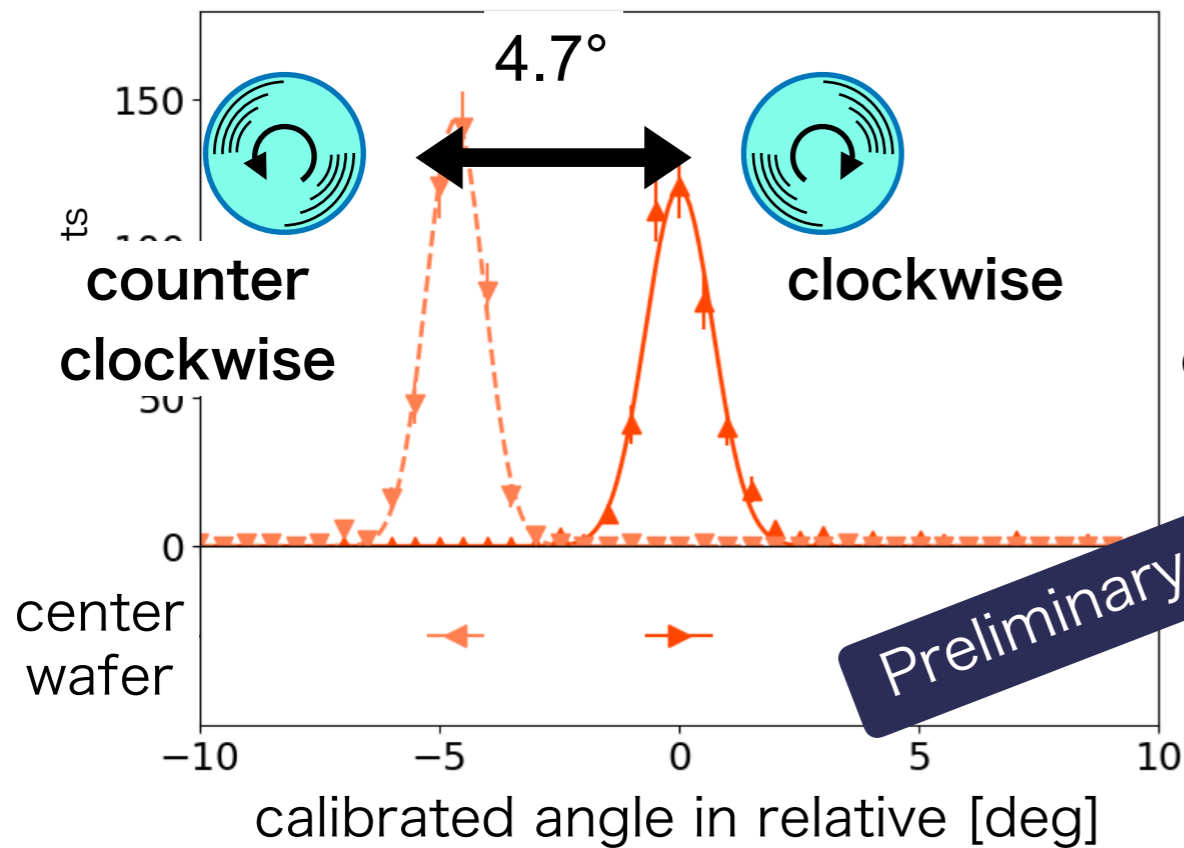
Due to the detectors' time constant, the signal delays as a function of HWP speed

Calibration at +/- 2 Hz HWP rotation



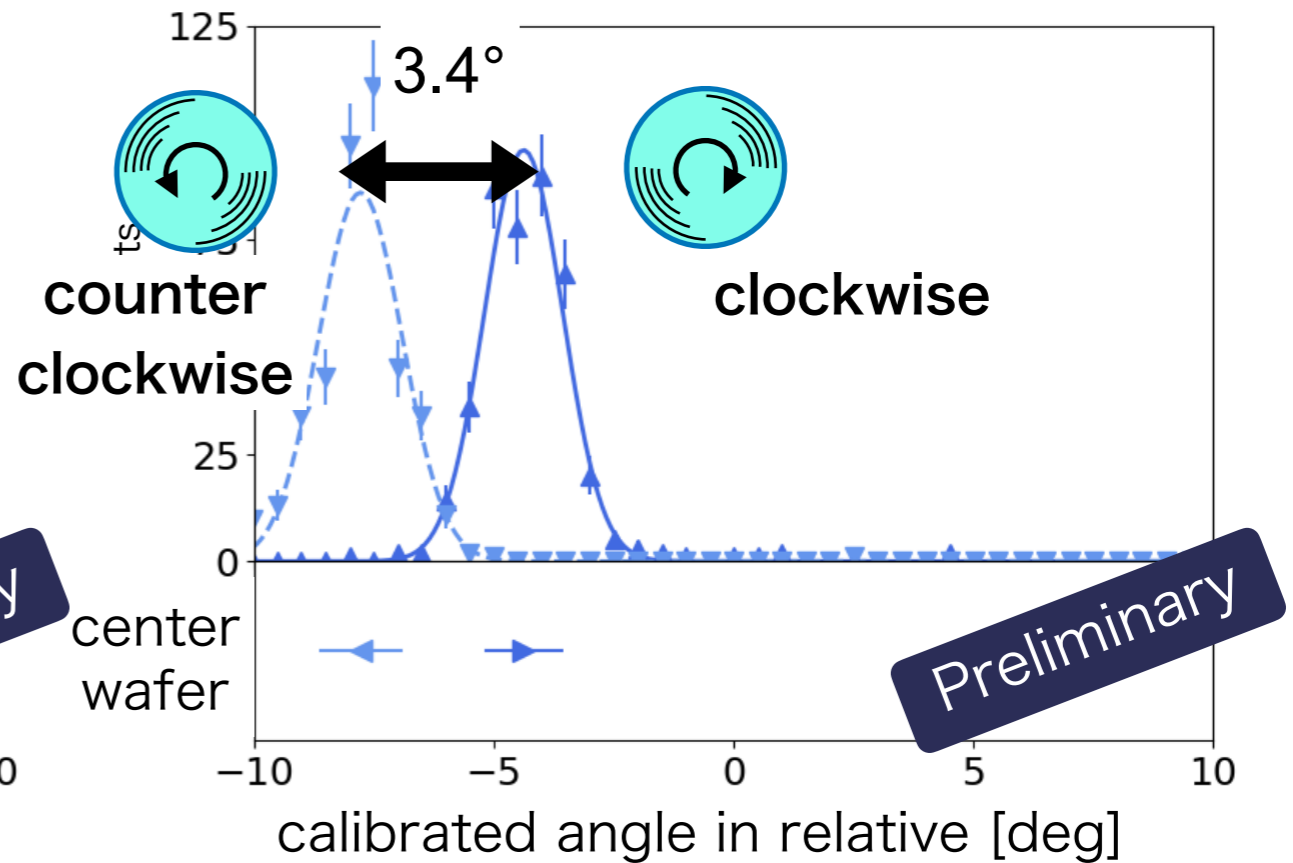
90 GHz

Calibrated Angle Stats.



150 GHz

Calibrated Angle Stats.

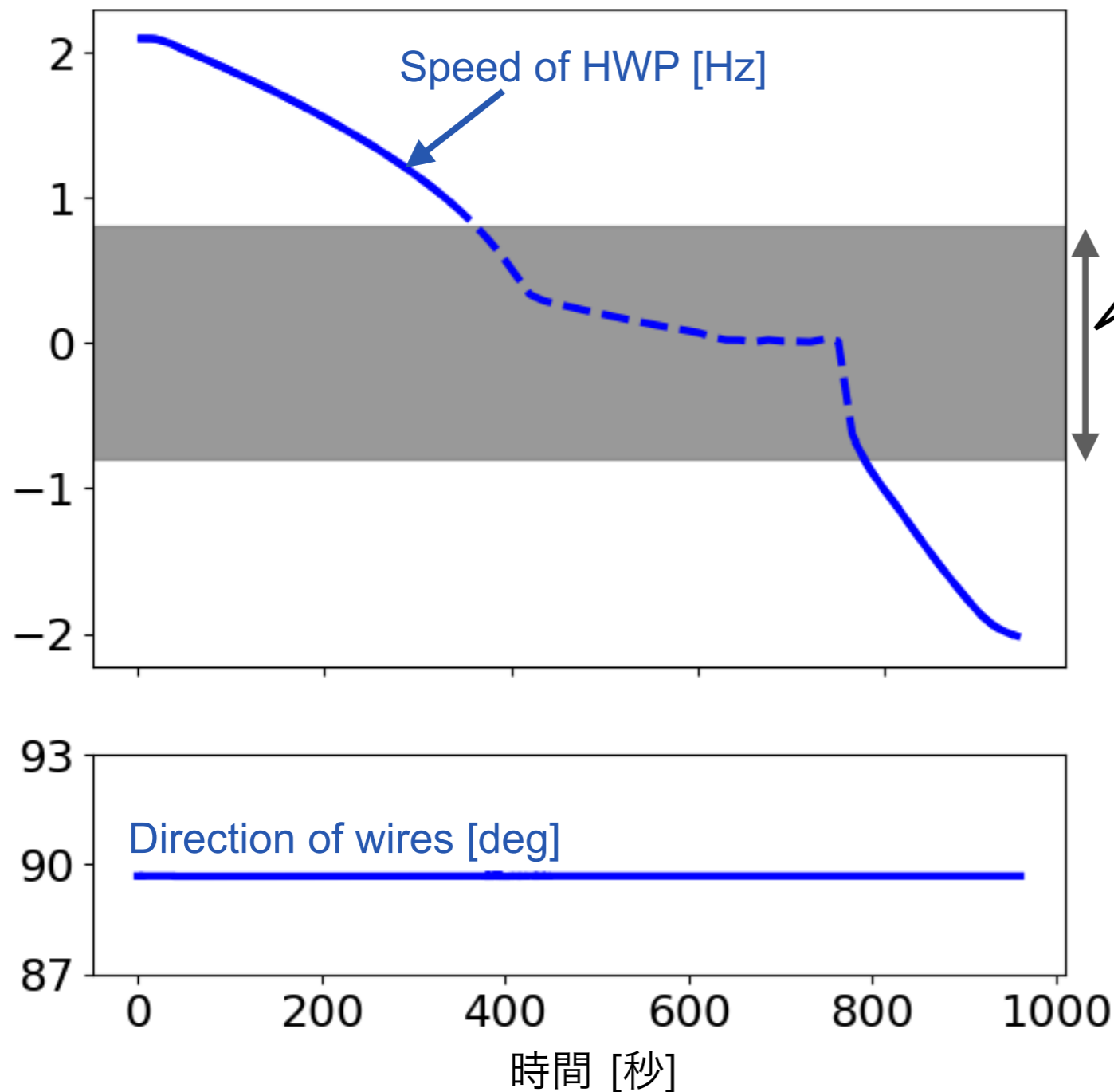


- The angle difference between +2Hz and -2Hz due to the time constant can be seen.

Operation for time constant measurement



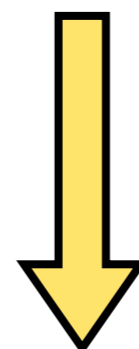
HWP/wire grid status during time const. measurement



This range is not used in the analysis because of picking up mechanical/electrical noise.

time const. dependence

$$\text{TOD} \propto \exp i \left[-4(\theta_{\text{HWP}} - \tau_{\text{det}} \omega_{\text{HWP}}) + 2(\theta_{\text{wire}} + \hat{\theta}_{\text{det}}) \right]$$



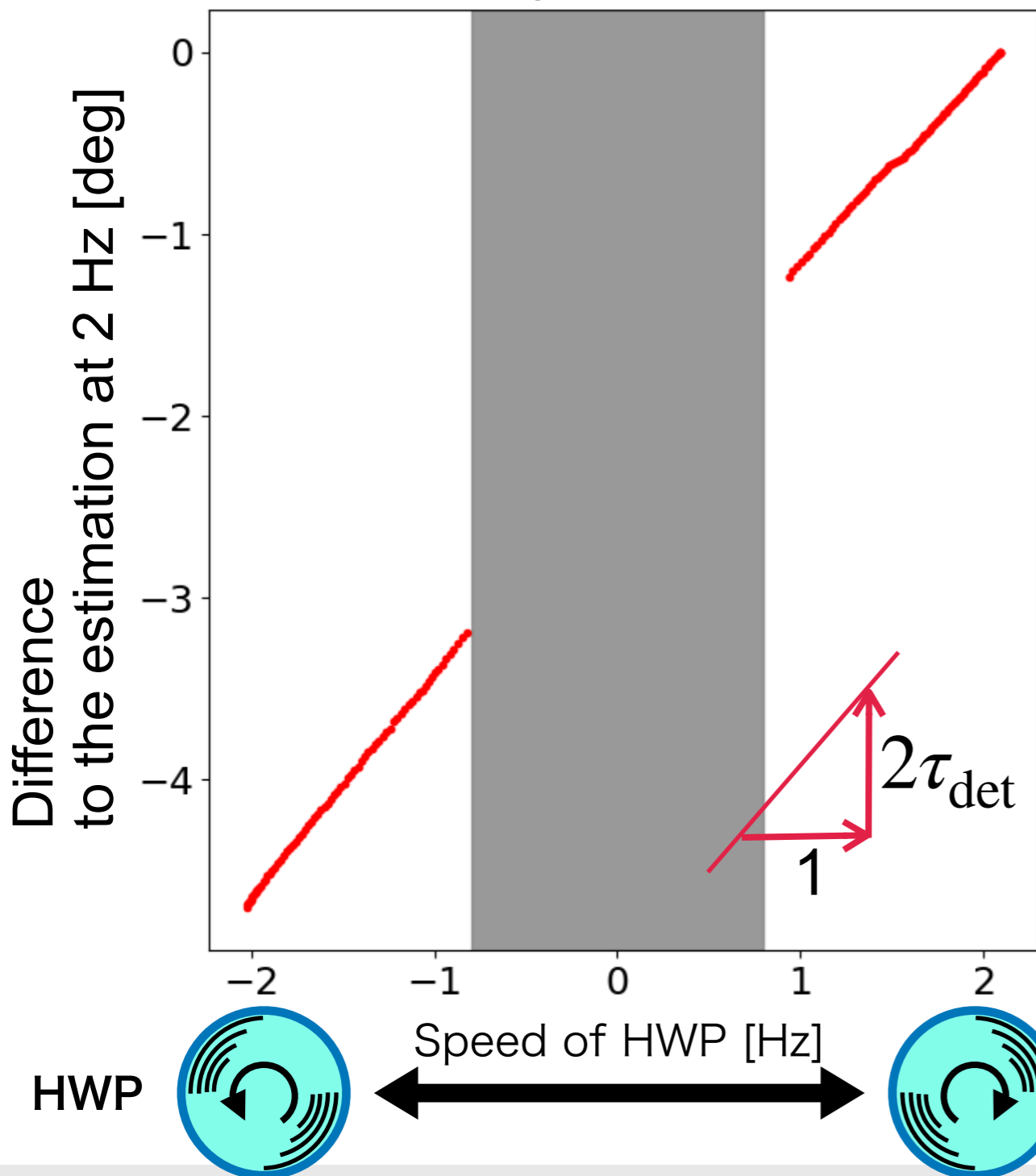
$$\theta_{\text{det}} = \hat{\theta}_{\text{det}} + 2\tau_{\text{det}} \omega_{\text{HWP}}$$

effects on calibration

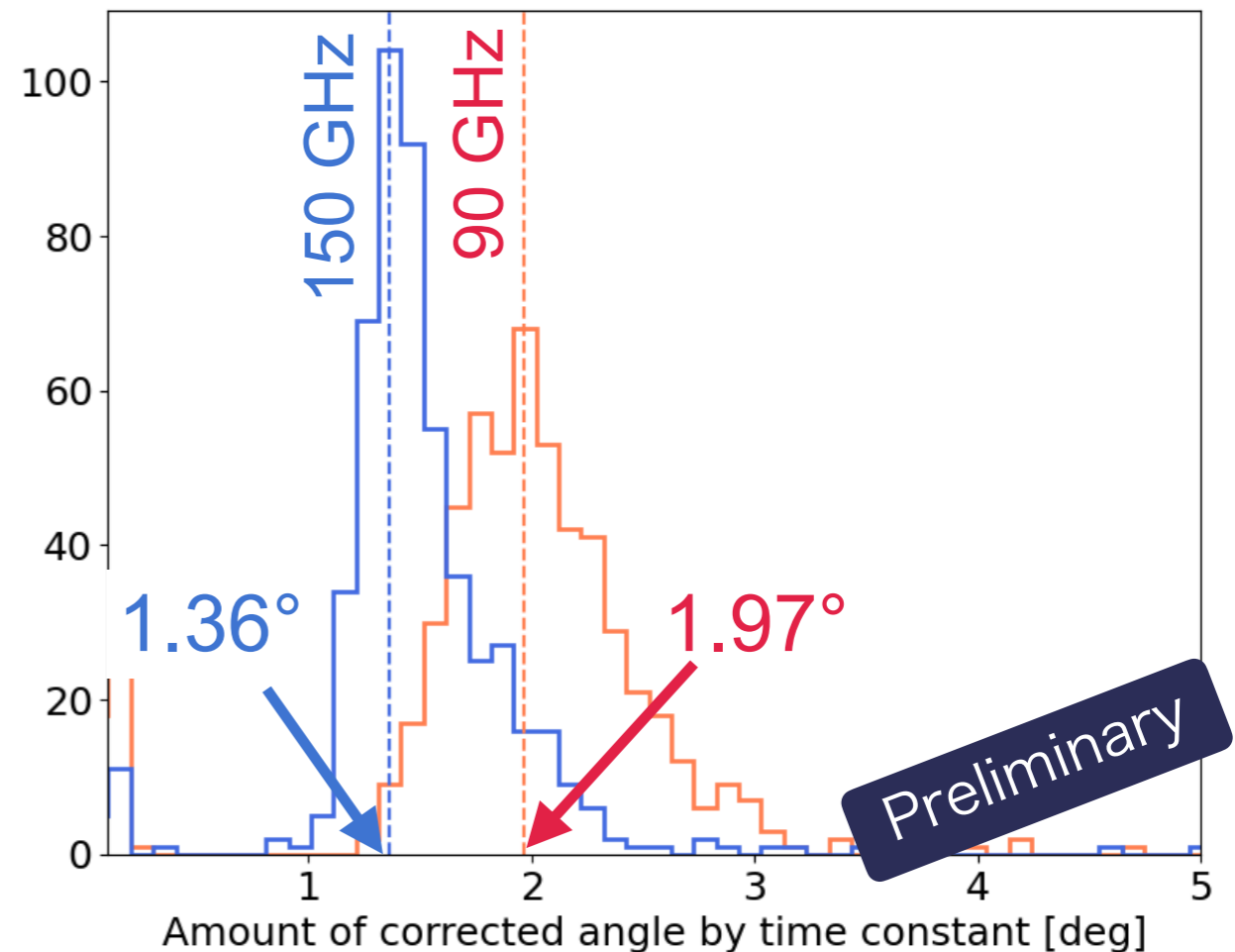
How to derive the time constants



Changing of the calibrated angle about the single detector



Angle correction for one direction



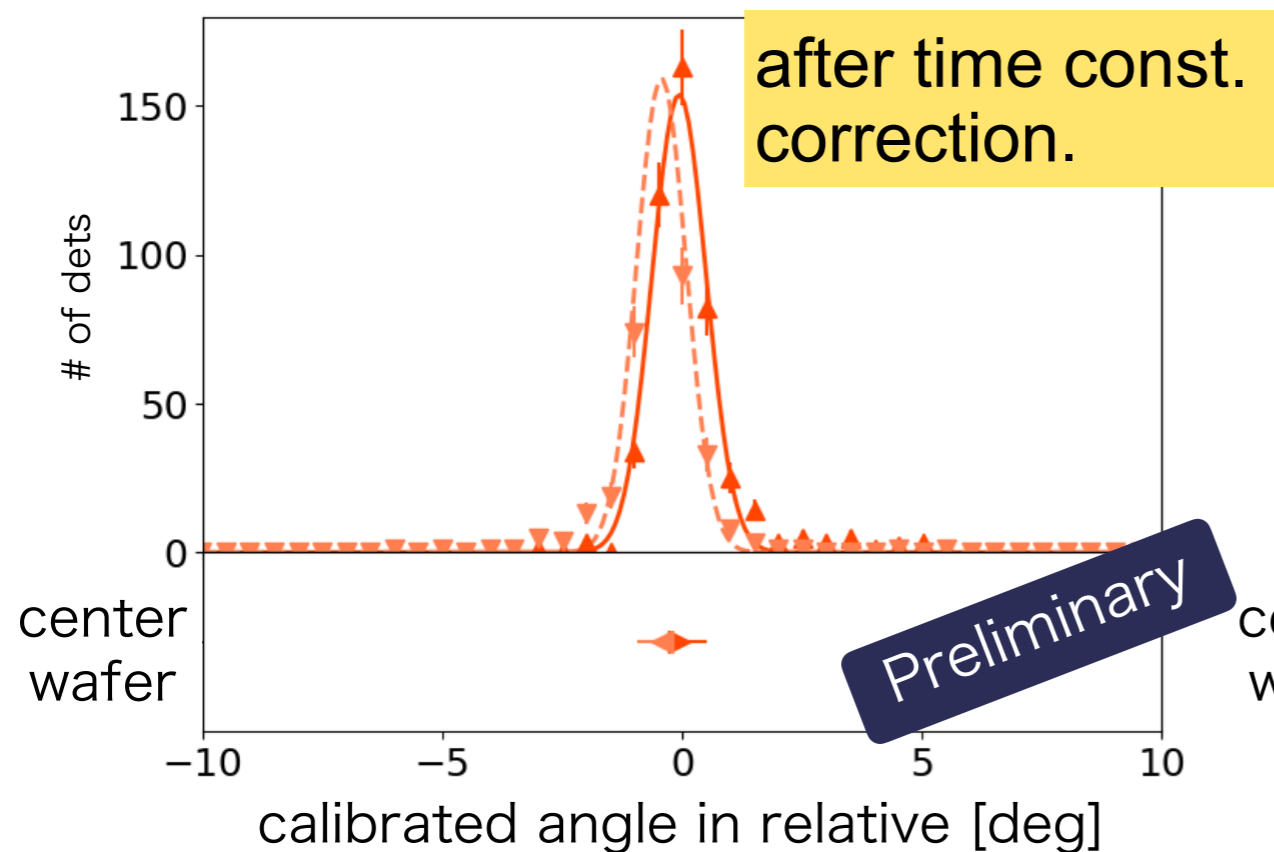
$$\theta_{\text{det}} = \hat{\theta}_{\text{det}} + 2\tau_{\text{det}} \omega_{\text{HWP}}$$

slope = time constant

After the correction

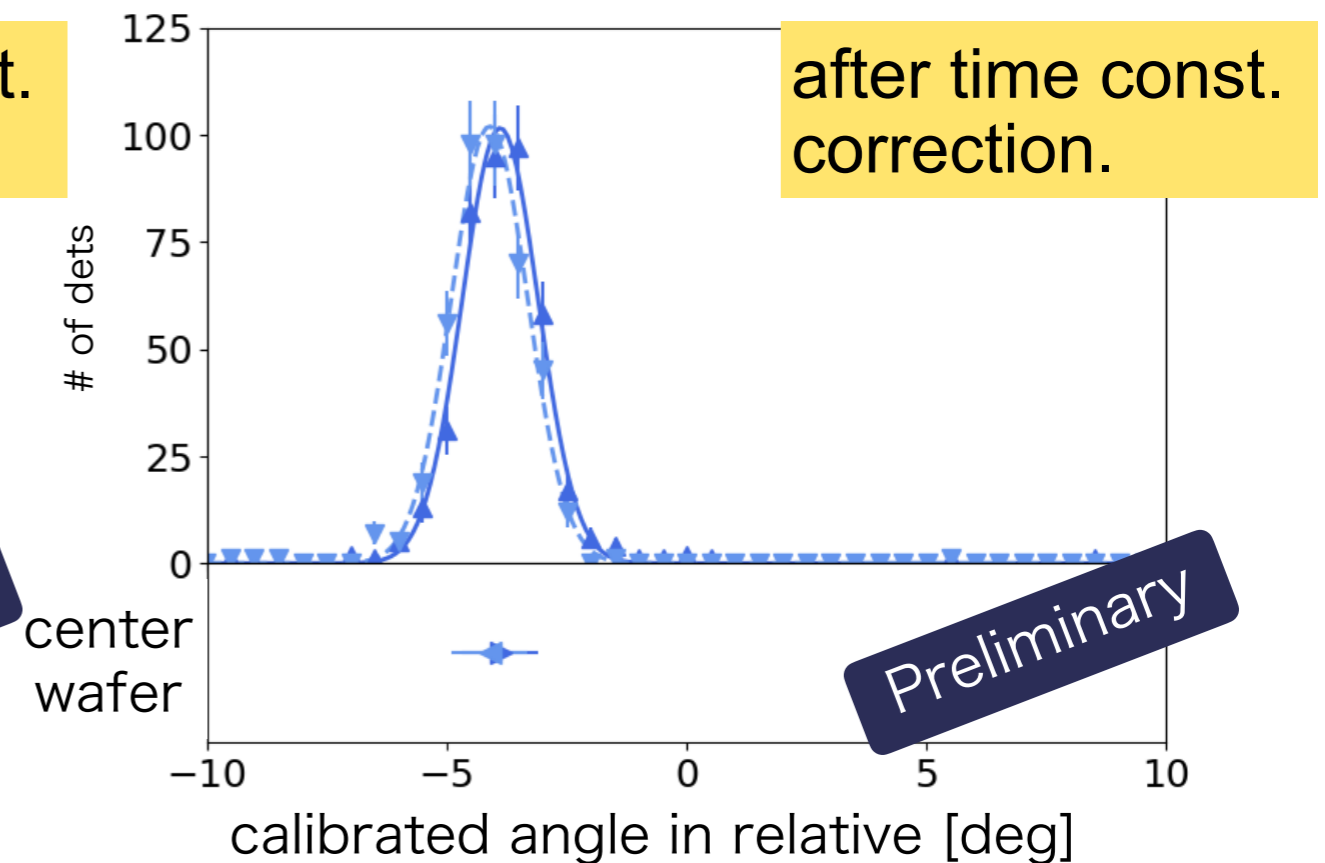
90 GHz

Calibrated Angle Stats.



150 GHz

Calibrated Angle Stats.



- The time constant correction works successfully!

Summary



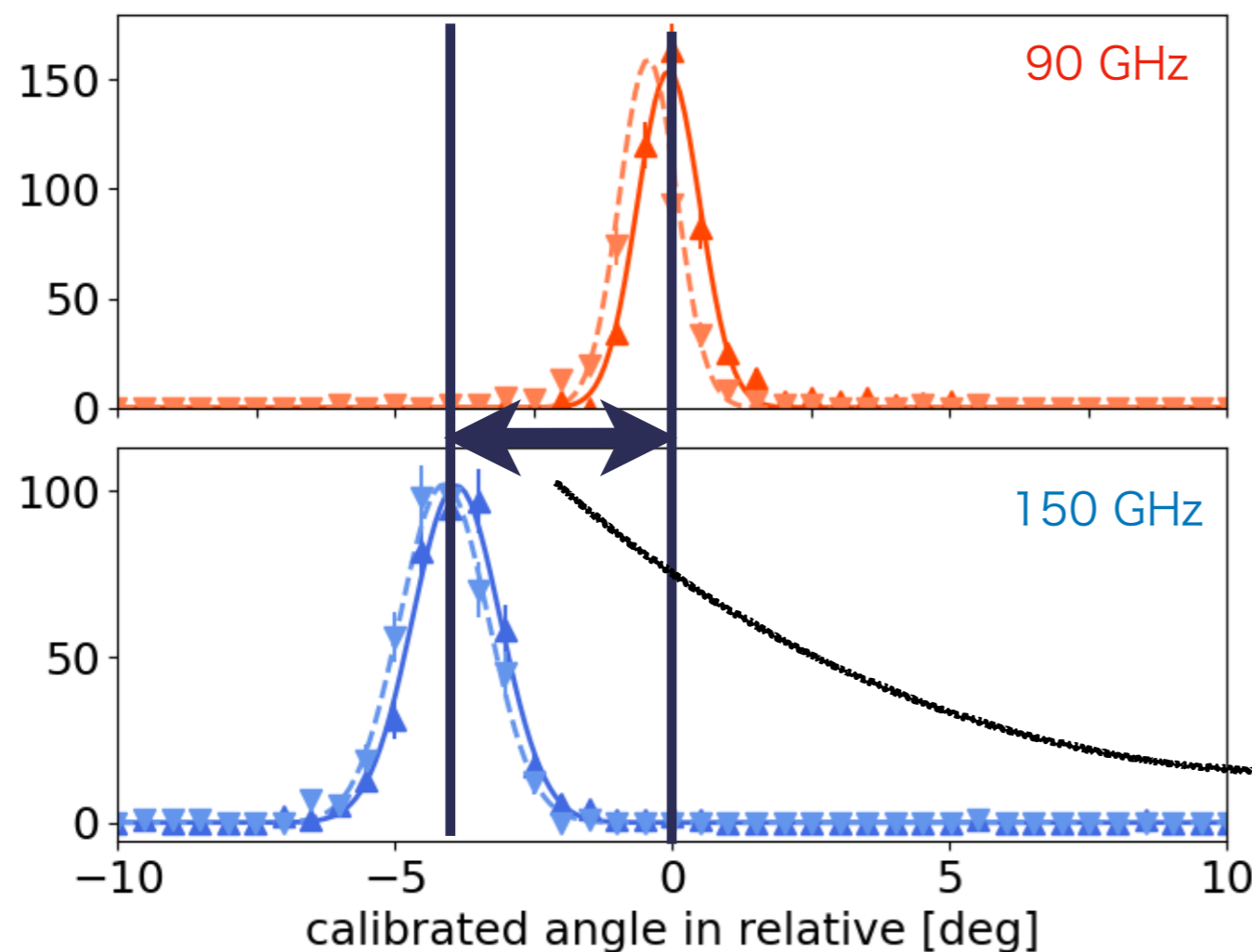
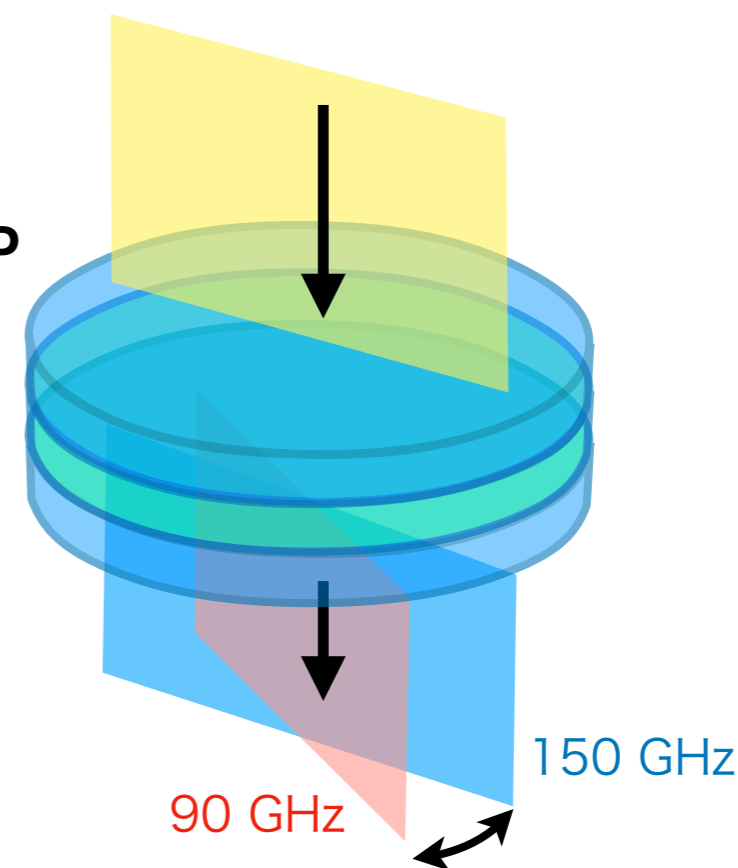
- Very precise polarization angle calibration, $\sigma(\theta_{\text{stat, sys}}) \leq 0.2$ deg., is required to measure the primordial B-mode with $\sigma(r) = 0.003$.
- We have developed an **automatic** calibration system using Sparse Wire Grid, which can **calibrate all the detector simultaneously** and **provides the reproducible calibrations** in just 10-mins. run.
- We have validated the methodology **with the site data**. Further, we successfully **measured the bolometer time constant** using sparse wire grid and HWP rotation
- In future plan: to combine the results with other complementary methods, drone and Tau A.

Backup



Effect of the Achromatic HWP

Achromatic HWP



$$\theta_{\text{HWP}, \Delta 90/150}^{\text{design}} \approx 1.9^\circ$$

Consistent!

$$\begin{aligned} \text{Diff.} &= 2 \times \theta_{\text{HWP}, \Delta 90/150}^{\text{measured}} \\ &= 2 \times 1.905^\circ \end{aligned}$$